diveMove: dive analysis in R

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Contents

1 Introduction

Dive analysis usually involves handling of large amounts of data, as new instruments allow for frequent sampling of variables over long periods of time. The aim of this package is to make this process more efficient for summarizing and extracting information gathered by time-depth recorders (TDRs, hereafter). The principal motivation for developing `diveMove` was to provide more flexibility during the various stages of

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Table 1. Sample TDR file structure.

date	time	depth	light	temperature	velocity
16/02/2004	14:30:00	12	200	8.4	1.44
16/02/2004	14:30:05	15	180	8.0	1.75
16/02/2004	14:30:10	19	170	7.6	1.99
. . .	. . .	. . .	. . .	. . .	. . .

analysis than that offered by popular commercial software. This is achieved by making the results from intermediate calculations easily accessible, allowing the user to make his/her own summaries beyond the default choices the package provides. The following sections of this vignette illustrate a typical work flow during analysis of TDR data, using the `sealMK8` data available in `diveMove` as an example.

2 Starting up

As with other packages in R, to use the package we load it with the funtion `library`:

```
> library(diveMove)
```

This makes the objects in the package available in the current R session. A short overview of the most important functions can be seen by running the examples in the package's help page:

```
> example(diveMove)
```

3 Reading Input Files

Input files must be simple, comma-delimited text files[1]. The order of columns is not significant, as the column numbers indicating the variables of interest can be supplied as arguments. Table 1 shows the file structure that readTDR assumes by default, which is a standard structure of files from common TDR models.

Depending on the TDR model, velocity may be omitted. Currently, light, temperature and any other variables beyond column 6 are ignored.

To read the file into R , use the function `readTDR`:

```
> sealX <- readTDR(system.file(file.path("data",
+     "sealMK8.csv"), package = "diveMove"))
```

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[1]The extension does not matter, but conventionally these files have a .csv extension

Read the help page for `readTDR` using `?readTDR` following common R help facilities. Thus, data could have been subsampled at a larger interval than that in the original file, so that the time interval between readings is 10 s:

```
> sealX <- readTDR(system.file(file.path("data",
+     "sealMK8.csv"), package = "diveMove"), subsamp = 10)
```

But since the original 5 s interval (which is the default value for *subsamp*) is what will be used for the subsequent sections, it is recreated it here:

```
> sealX <- readTDR(system.file(file.path("data",
+     "sealMK8.csv"), package = "diveMove"))
```

The format in which date and time should be interpreted can be controlled with the argument *dtformat*. If the data are already available in the R session, e.g. as a **data frame**, then the function `createTDR` can be used to convert it to a form that facilitates further analyses.

Both of these functions store the data in an object of class *TDR* or *TDRvel*, which hold information on the source file and sampling interval, in addition to the variables described above. Which of these objects is created is determined by the name of the input file. All files should contain the letter sequence "mk" followed by a number, as these correspond to the names of common TDR models. If the number following this sequence is 8, then a *TDRvel* object is created, otherwise the function returns a *TDR* object.

4 Extraction and Display of Information from TDR and TDRvel Objects

For convenience, extractor methods are available to access the different slots from objects of these classes. The standard *show* method will display the usual overview information on the object:

```
> sealX
```

```
Time-Depth Recorder data -- Class TDRvel object
  Source File            : sealMK8.csv
  Sampling Interval (s)  : 5
  Number of Samples      : 34199
  Sampling Begins        : (05/01/02 11:32:00)
  Sampling Ends          : (07/01/02 11:01:50)
  Total Duration (d)     : 1.979
```

Other extractor methods are named after the component they extract: *getTime*, *getDepth*, *getVeloc*, and *getDtime*, where the latter extracts the sampling interval. The *plot* method brings up a plot of the data covering the entire record, although a `tcltk` widget provides controls for zooming and panning to any particular time window. Alernatively, the underlying function `plotDive` provides the same functionality, but takes separate *time* and *depth* arguments, rather than a *TDR* object.

At any time, TDR objects can be coerced to a simple data frame, which can later be exported or manipulated any other way:

```
> sealX.df <- as.data.frame(sealX)
> head(sealX.df)


                  time depth velocity
1 (05/01/02 11:32:00)    NA       NA
2 (05/01/02 11:32:05)    NA       NA
3 (05/01/02 11:32:10)    NA       NA
4 (05/01/02 11:32:15)    NA       NA
5 (05/01/02 11:32:20)    NA       NA
6 (05/01/02 11:32:25)    NA       NA
```

5 Zero-Offset Depth Correction and Summary of Wet/Dry Periods

One the first steps of dive analysis involves correcting depth for shifts in the pressure transducer, so that surface readings correspond to the value zero. Although some complex algorithms exist for detecting where these shifts occur in the record, the shifts remain difficult to detect and dives are often missed, which a visual examination of the data would have exposed. The trade off is that visually zero-adjusting depth is tedious, but the advantages of this approach far outweigh this cost, as much insight is gained by visually exploring the data. Not to mention the fact that obvious problems in the records are more effectively dealt with in this manner.

That personal rant aside, zero offset correction (ZOC) is done in `diveMove` using the function `zoc`. However, a more efficient method of doing this is by using the `calibrateDepth` function, which takes a *TDR* object (or inheriting from it) to perform three basic tasks. The first is to ZOC the data, using the `tcltk` package to be able to do it interactively:

```
> dcalib <- calibrateDepth(sealX)
```

This command brings up a plot with `tcltk` controls allowing to pan and zoom in or out of the data, as well as adjustment of the `depth` scale. Thus, an appropriate time

window with a unique surface depth value can be displayed. It is important to make the display such that the `depth` scale is small enough to allow the resolution of the surface value with the mouse. Clicking on the ZOC button waits for two clicks:

1. the coordinates of the first click define the starting time for the window to be ZOC'ed, and the depth corresponding to the surface,
2. the second click defines the end time for the window (only the x coordinate has any meaning).

This procedure can be repeated as many times as needed. If there is any overlap between time windows, then the last one prevails. However, if the offset is known a priori, there is no need to go through all this procedure, and the value can be provided as the argument *offset* to `calibrateDepth`.

Once depth has been ZOC'ed, `calibrateDepth` will identify dry and wet periods in the record. Wet periods are those where a depth reading is available, dry periods are those without a depth reading. Records often have abherrant missing depth that should not be considered dry periods, as they are often of very short duration. Likewise, there may be periods of wet activity that are too short to be compared with other wet periods. This can be controlled by setting the arguments *landerr* and *seaerr*.

Finally, `calibrateDepth` identifies all dives in the record, according to a minimum depth criteria given as its *divethres* argument. The result (value) of this function is an object of class *TDRcalibrate*, where all the information obtained during the tasks described above are stored. Again, an appropriate *show* method is available to display a short overview of such objects:

```
> dcalib


Depth calibration -- Class TDRcalibrate object
  Source file                     : sealMK8.csv
  Number of dry phases            : 4
  Number of aquatic phases        : 3
  Number of dives detected        : 317
  Dry threshold used (s)          : 65
  Aquatic theshold used (s)       : 3605
  Dive threshold used (s)         : 4
  Velocity calibration coefficients : a = 0 ; b = 1
```

6 Access to Elements from TDRcalibrate Objects

Extractor methods are also available to access the information stored in *TDRcalibrate* objects. These include: *getTDR*, *getGAct*, *getDAct*, *getDPhaseLab*, and *getVelCoefs*.

These are all generic functions[2] that access the (depth) calibrated *TDR* object, details from wet/dry periods, dives, dive phases, and velocity calibration coefficients (see Section 7), respectively. Below is a short explanation of these methods.

getTDR This method simply takes the *TDRcalibrate* object as its single argument and extracts the *TDR* object[3]:

```
> getTDR(dcalib)

Time-Depth Recorder data -- Class TDRvel object
  Source File           : sealMK8.csv
  Sampling Interval (s)  : 5
  Number of Samples      : 34199
  Sampling Begins        : (05/01/02 11:32:00)
  Sampling Ends          : (07/01/02 11:01:50)
  Total Duration (d)     : 1.979
```

getGAct There are two methods for this generic, allowing access to a list with details about all wet/dry periods found. One of these extracts the entire *list* (output omitted for brevity):

```
> getGAct(dcalib)
```

The other provides access to particular elements of the *list*, by their name. For example, if we are interested in extracting only the vector that tells us to which period number every row in the record belongs to, we would issue the command:

```
> getGAct(dcalib, "phase.id")
```

Other elements that can be extracted are named "trip.act", "trip.beg", and "trip.end", and can be extracted in a similar fashion. These elements correspond to the activity performed for each reading (see ?detPhase for a description of the labels for each activity), the beginning and ending time for each period, respectively.

getDAct This generic also has two methods; one to extract an entire data frame with details about all dive and postdive periods found (output omitted):

```
> getDAct(dcalib)
```

The other method provides access to the columns of this data frame, which are named "dive.id", "dive.activity", and "postdive.id". Thus, providing any one of these strings to getDAct, as a second argument will extract the corresponding column.

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[2]A few of them with more than one method

[3]In fact, a *TDRvel* object in this example

getDPhaseLab This generic function extracts a factor identifying each row of the record to a particular dive phase (see `?detDive` for a description of the labels of the factor identifying each dive phase). Two methods are available; one to extract the entire factor, and the other to select particular dive(s), by its (their) number, respectively (output omitted):

```
> getDPhaseLab(dcalib)
> getDPhaseLab(dcalib, 20)

> dphases <- getDPhaseLab(dcalib, c(100:300))
```

The latter method is useful for visually inspecting the assignment of points to particular dive phases. Before doing that though, this is a good time to introduce another generic function that allows the subsetting of the original *TDR* object to a single a dive or group of dives' data:

```
> subSealX <- extractDive(dcalib, diveNo = c(100:300))
> subSealX

Time-Depth Recorder data -- Class TDRvel object
  Source File            : sealMK8.csv
  Sampling Interval (s)   : 5
  Number of Samples       : 2410
  Sampling Begins         : (06/01/02 00:45:15)
  Sampling Ends           : (07/01/02 03:27:10)
  Total Duration (d)      : 1.112
```

As can be seen, the function takes a *TDRcalibrate* object and a vector indicating the dive numbers to extract, and returns a *TDR* object containing the subsetted data. Once a subset of data has been selected, it is possible to plot them and pass the factor labelling dive phases as the argument *phaseCol* to the *plot* method[4]:

```
> plot(subSealX, phaseCol = dphases)
```

7 Velocity Calibration

Calibration of velocity readings is done using the principles described in Blackwell (1999) and Hindell et al. (1999). The function `calibrateVel` performs this operation[5], and allows the selection of the particular subset of the data that should be used for the calibration:

---

[4]The function that the method uses is actually `plotDive`, so all the possible arguments can be studied by reading the help page for `plotDive`

[5]CAUTION: This implementation is experimental, and may give unexpected results.

```
> vcalib <- calibrateVel(dcalib, calType = "pooled")

> vcalib


Depth calibration -- Class TDRcalibrate object
  Source file                    : sealMK8.csv
  Number of dry phases           : 4
  Number of aquatic phases       : 3
  Number of dives detected       : 317
  Dry threshold used (s)         : 65
  Aquatic theshold used (s)      : 3605
  Dive threshold used (s)        : 4
  Velocity calibration coefficients : a = 0.4 ; b = 0.64
```

A side effect of such a call is the production of a plot displaying the quantile regression fit for the three phases (Figure 1). This can be displayed on the current device, or sent to a postscript file, using postscript=TRUE in the call, for a higher quality representation.

The default (calType="pooled") is to use data from the descent and ascent phases of all dives, but possible values also include "descent", "ascent", and "none". Because the function produces three plots of velocity vs. rate of depth change, the latter is useful in cases where velocity does not need any calibration, but inspection of the plots is desired. Finer control is possible by the use of arguments *type*, which controls whether descent or ascent readings that are shared with the bottom phase of the dive should be included or not, and *bad*, which controls minimum velocities and rates of depth change through which the calibration line should be drawn. Finally, a maximum depth threshold can be supplied as the argument z, so that only data from dives where maximum depth was greater than this value are included in the construction of the calibration line.

If the calibration coefficients from the implicit quantile regression are known a priori, then these can be supplied to the function via its *coefs* argument. In this case, no plots are created.

8 TDR dive and postdive statistics

Once data have been calibrated and the record broken up at "trip" and "dive" scales, obtaining dive statistics is a trivial call to function diveStats:

```
> dives <- diveStats(vcalib)
> head(dives, 3)
```

sealMK8 −− descent

$y = 0.428 + 0.469x$

sealMK8 −− ascent

$y = 0.307 + 0.999x$

sealMK8 −− pooled
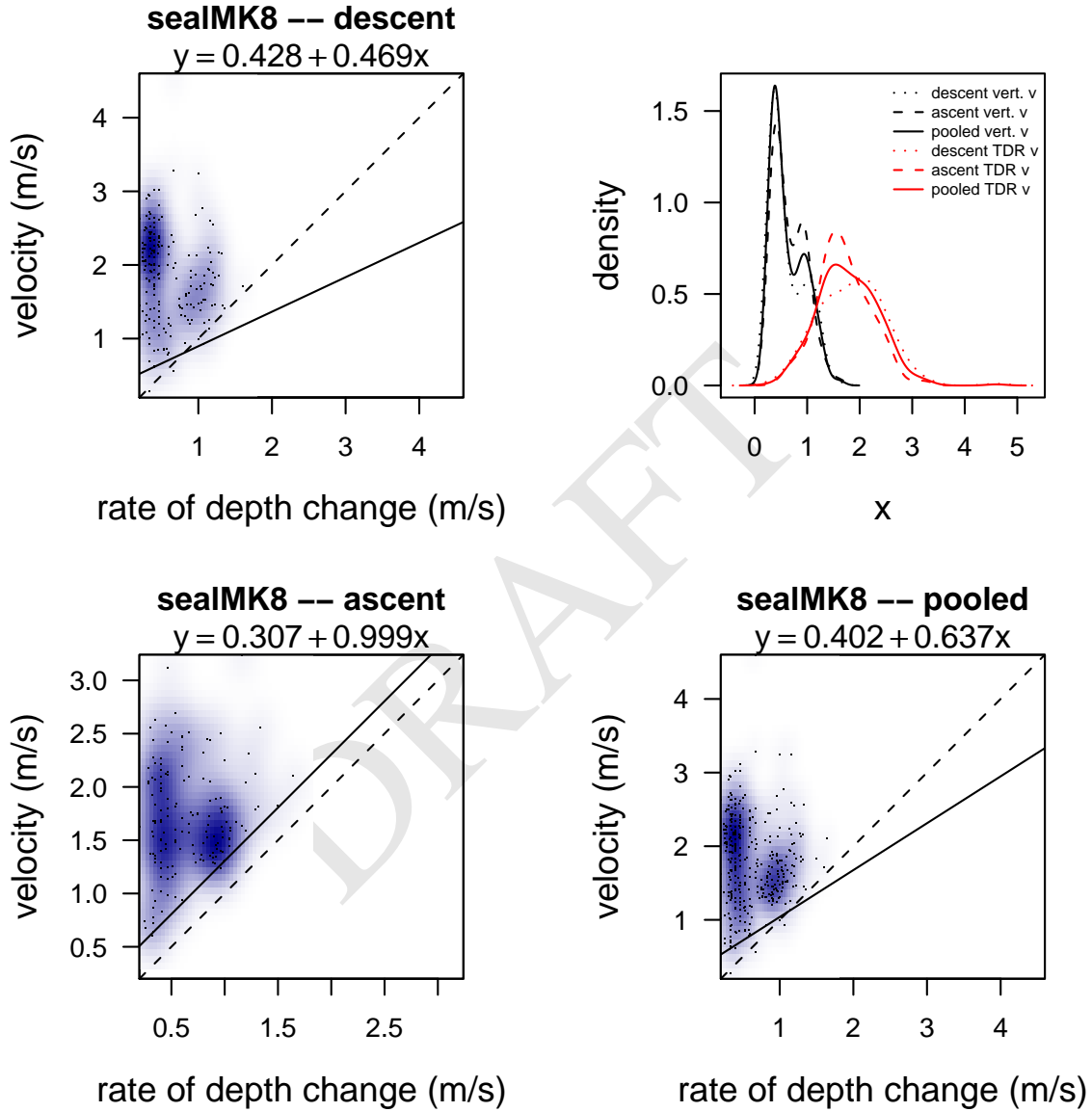
$y = 0.402 + 0.637x$

Figure 1. Example velocity calibration lines, dividing dives into descent, ascent, or pooling both phases from a TDR record.

```
            begdesc            enddesc
1 (01/05/02 12:20:10) (01/05/02 12:20:15)
2 (01/05/02 21:19:40) (01/05/02 21:20:20)
3 (01/05/02 21:22:10) (01/05/02 21:23:15)
              begasc desctim botttim asctim descdist
1 (01/05/02 12:20:20)    7.5       5    7.5        6
2 (01/05/02 21:20:40)   42.5      20   47.5       26
3 (01/05/02 21:23:50)   67.5      35   72.5       63
  bottdist ascdist desc.tdist desc.mean.vel desc.angle
1        0       6      22.44         4.488      15.51
2        3      29     100.07         2.502      15.06
3        8      67     107.84         1.659      35.75
  bott.tdist bott.mean.vel asc.tdist asc.mean.vel asc.angle
1      15.22         3.043     18.04        3.609     19.42
2      53.96         2.698     71.78        1.595     23.83
3      56.11         1.603     98.09        1.401     43.08
  divetim maxdep postdive.dur postdive.tdist
1      20      6        32345       50445.70
2     110     29           35          16.85
3     175     67           75          58.18
  postdive.mean.vel
1            1.5652
2            0.4815
3            0.7758
```

The function takes a single argument: an object of class *TDRcalibrate*, and returns a data frame with one row per dive in the record, with a suite of basic dive statistics in each column. Please consult `?diveStats` for an explanation of each of the variables estimated, although the names of the output data frame should be self explanatory. These variables are thus available for calculating any other derived values, by extracting them using the standard R subscripting facilities.

9 Miscellaneous functions

Other functions are included for handling location data, and these are `readLocs`, `austFilter`, and `distSpeed`. These are useful for reading, filtering, and summarizing travel information. For extensive animal movement analyses, refer to package `timeTrack` available at http://staff.acecrc.org.au/~mdsumner/Rutas/.

10 Acknowledgements

Invaluable input and help during development of this package has been offered by John P.Y. Arnould, and regular contributors to R-help.

References

Blackwell, S. (1999). A method for calibrating swim-speed recorders. *Marine Mammal Science*, 15(3):894–905.

Hindell, M., McConnell, B., Fedak, M., Slip, D., Burton, H., Reijnders, P., and McMahon, C. (1999). Environmental and physiological determinants of successful foraging by naive southern elephant seal pups during their first trip to sea. *Canadian Journal of Zoology*, 77:1807–1821.

diveMove

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R topics documented:

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austFilter	*Filter satellite locations*

Description

Apply a three stage algorithm to eliminate erroneous locations, based on the procedure outlined in Austin et al. (2003).

Usage

```
austFilter(time, lon, lat, id=gl(1, 1, length(time)),
           velthres, distthres, window=5)
grpSpeedFilter(x, velthres, window=5)
rmsDistFilter(x, velthres, window=5, distthres)
```

Arguments

`time`	chron object with dates and times for each point.
`lon`	numeric vectors of longitudes, in decimal degrees.
`lat`	numeric vector of latitudes, in decimal degrees.
`id`	a factor grouping points in different categories (e.g. individuals).
`velthres`	velocity threshold above which filter tests should fail any given point.
`distthres`	distance threshold above which the last filter test should fail any given point.
`window`	integer indicating the size of the moving window over which tests should be carried out.
`x`	3-column matrix with column 1: numeric chron vector; column 2: numeric longitude vector; column 3: numeric latitude vector.

Details

These functions implement the location filtering procedure outlined in Austin et al. (2003). `grpSpeedFilter` and `rmsDistFilter` can be used to perform only the first stage or the second and third stages of the algorithm on their own, respectively. Alternatively, the three filters can be run sequentially using `austFilter`.

The first stage of the filter is an iterative process which tests every point, except the first and last two, for travel velocity relative to the preceeding/following two points. If all these four velocities are greater than the specified threshold, the point is marked as failing the first stage. In this case, the next point is tested, removing the failing point from the set of test points.

The second stage runs McConnell et al. (1992) algorithm, which tests all the points that passed the first stage, in the same manner as above. The root mean square of all four velocities is calculated, and if it is greater than the specified threshold, the point is marked as failing the second stage.

The third stage is run simultaneously with the second stage, but if the mean distance of all four pairs of points is greater than the specified threshold, then the point is marked as failing the third stage.

Value

A matrix with three columns of logical vectors with values TRUE for points that failed each stage.

Warning

This function applies McConnell et al.'s filter as described in Austin et al. (2003), but other authors may have used the filter differently. Austin et al. (2003) have apparently applied the filter in a vectorized manner. It is not clear from the original paper whether the filter is applied iteratively or in a vectorized fashion, so authors may be using it inconsistently.

Note

Points that fail the first stage also fail the second and third stage, but points that fail the second stage do not necessarily fail the third stage.

Author(s)

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References

McConnell BJ, Chambers C, Fedak MA. 1992. Foraging ecology of southern elephant seals in relation to bathymetry and productivity of the Southern Ocean. *Antarctic Science* 4:393-398.

Austin D, McMillan JI, Bowen D. 2003. A three-stage algorithm for filtering erroneous Argos satellite locations. *Marine Mammal Science* 19: 371-383.

See Also

distSpeed

---

calibrateDepth   *Calibrate and build a "TDRcalibrate" object*

Description

These functions create a "TDRcalibrate" object which is necessary to obtain dive summary statistics.

Usage

```
calibrateDepth(x, landerr=65, seaerr=3605, divethres=4, offset)
calibrateVel(x, type="all", calType="pooled", bad=c(0, 0),
z=0, filename=slot(getTDR(x), "file"), coefs, ...)
```

Arguments

x	an object of class TDR for calibrateDepth, and an object of class TDRcalibrate-class for calibrateVel.
landerr, seaerr	arguments to detPhase.
divethres	argument to detDive.
offset	argument to zoc.
type, calType, bad, z, filename	further arguments for .getVelCalib and doVelCalib.
coefs	known velocity calibration coefficients from quantile regression as a vector of length 2 (intercept, slope). If provided, these coefficients are used for calibrating velocity, ignoring all other arguments, except x.
...	argument passed to doVelCalib.

Details

These functions are really wrappers around functions that are usually called in sequence, so they provided an abbreviated method for running them together during analyses. See the functions in the 'See Also' section for more details.

calibrateDepth performs zero-offset correction of depth, wet/dry phase detection, and detection of dives, as well as proper labelling of the latter.

calibrateVel calibrates velocity readings.

Value

An object of class TDRcalibrate-class

Author(s)

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See Also

detPhase, detDive, doVelCalib, zoc, for the underlying functions.

---

detDive   *Detect dives from depth readings*

Description

Identify dives in TDR records based on a dive threshold.

Usage

```
detDive(time, zdepth, act, divethres=4, ...)
labDive(time, act, string, interval)
labDivePhase(x, diveID)
```

Arguments

time	chron object specifying times for each depth reading. This is most commonly the first element of the data frame returned by readTDR.
zdepth	vector of zero-offset corrected depths.
act	factor as long as depth coding activity, with levels specified as in detPhase.
divethres	threshold depth below which an underwater phase should be considered a dive.
string	a character belonging to a level of act to search for and label sequentially.
interval, ...	the sampling interval in chron units (d).
x	a class 'TDR' object
diveID	numeric vector indexing each dive (non-dives should be 0)

Details

emph{detDive} detects a dive whenever the zero-offset corrected depth in an underwater phase is below the supplied dive threshold. The adjustment is done only for phases of at-sea activity, completely ignoring phases with other activity.

emph{labDive} assigns a unique number to each dive along a vector of depths, and equally numbering the subsequent postdive interval.

emph{labDivePhase} labels each row identifying it with a portion of the dive.

Value

A data frame with the following elements for `detDive`

dive.id	numeric vector numbering each dive in the record.
dive.activity	
	factor with levels 'L', 'W', 'U', 'D', and 'Z', see detPhase. All levels may be represented.
postdive.id	numeric vector numbering each postdive interval with the same value as the preceding dive.

`labDive` returns a matrix with as many rows as its first two arguments with two columns: dive.id, and postdive.id, each one sequentially numbering each dive and postdive period.

`labDivePhase` returns a factor with levels "D", "DB", "B", "BA", "A", "DA", and "X", breaking the input into descent, descent/bottom, bottom, bottom/ascent, ascent, and non-dive, respectively.

Author(s)

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See Also

detPhase, zoc

---

detPhase   *Detect phases of activity from depth readings*

Description

Functions to identify sections of a TDR record displaying one of three possible activities: on-land, at-sea, and at-sea leisure.

Usage

```
detPhase(time, depth, landerr=65, seaerr=3605, ...)
getAct(time, act, interval)
```

Arguments

time	chron object with date and time for all depths.
depth	numeric vector with depth readings.
landerr	land error threshold in seconds. On-land phases shorter than this threshold will be considered as at-sea.
seaerr	at-sea leisure threshold in seconds. At-sea phases shorter than this threshold will be considered as at-sea leisure.
act	A numeric vector indicating the activity for every element of time.
interval, ...	
	sampling interval in chron units (d).

Details

detPhase first creates a factor with value 'L' (on-land) for rows with NAs for depth and value 'W' (at-sea) otherwise. It subsequently calculates the duration of each of these phases of activity. If the duration of an on-land phase ('L') is less than landerr, then the values in the factor for that phase are changed to 'W' (at-sea). The duration of phases is then recalculated, and if the duration of a phase of at-sea activity is less than seaerr, then the corresponding value for the factor is changed to 'Z' (at-sea leisure). The durations of all phases are recalculated a third time to provide final phase durations.

getAct takes a factor indicating different activity phases, their associated time, and the sampling interval to return a factor uniquely identifying each phase of activity, i.e. labelling them. In addition, it returns the duration of each phase, and their beginning and end times.

Value

A list with components; the first 4 are returned by detPhase and the rest by getAct:

phase.id	numeric vector identifying each activity phase, starting from 1 for every input record.
trip.act	factor with levels 'L' indicating land, 'W' indicating at-sea, 'U' for underwater (above dive criterion), 'D' for diving, 'Z' for at-sea leisure animal activities. Only 'L', 'W', and 'Z' are actually represented.
trip.beg	a numeric vector as long as the number of unique activity phases identified, representing the time (in days) since the origin set by chron to the start times for each activity phase.
trip.end	a numeric vector as long as the number of unique activity phases identified, representing the time (in days) since the origin set by chron to the end times for each activity phase.
time.br	a factor dividing the factor act in phases.
time.peract	duration of each phase defined by time.br.
beg.time	beginning time for each phase.
end.time	ending time for each phase.

Author(s)

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See Also

detDive

---

distSpeed	*Calculate distance and speed between locations*

Description

Calculate distance, time difference, and velocity between pairs of points defined by latitude and longitude, given the time at which all points were measured.

Usage

```
distSpeed(pt1, pt2, velocity=TRUE)
track(txy, id=gl(1, nrow(txy)), subset)
```

Arguments

pt1   a matrix or data frame with three columns; the first a chron object with dates
           and times for all points, the second and third numeric vectors of longitude and
           latitude for all points, respectively, in decimal degrees.

pt2   a matrix with the same structure as pt1.

velocity   logical; should velocity between points be calculated?

txy   a data frame with a chron object in its first column, lon and lat in second and
           third column, respectively.

id   a factor dividing the data in txy into distinct groups.

subset   a logical expression indicating the rows to be analyzed, in terms of elements of
           txy.

Details

pt1 and pt2 may contain any number of rows. track is essentially a wrapper for distSpeed,
taking a data frame, assumed to be ordered chronologically, and calculations are done between all
successive rows.

Value

For distSpeed, a matrix with three columns: distance (km), time difference (h), and velocity
(m/s). For track, a data frame with an id column and the same columns as in distSpeed.

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---

diveMove-internal   *Internal diveMove Functions*

Description

Functions used for very particular tasks within larger functions in diveMove

Usage

```
.cutDive(x)
.createChron(date, time, dtformat)
.descAsc(x, phase, type=c("all", "strict"), interval, z=0)
.getInterval(time)
.getVelCalib(time, zdepth, vel, dives, phase, ...)
.getVelStats(x, vdist)
```

Arguments

x	a single dive's data; for `.cutDive`: a 2-col matrix with subscript in original TDR object and non NA depths. For *.descAsc*: a 4-col matrix with dive id, time, depth, and velocity. For *.getVelStats*: a 3-col matrix with time, depth, and velocity.
date	A vector to be converted to be converted to a chron object.
time	chron object representing time, or a vector to be converted to such an object (for `.createChron`). It can be missing in the latter case.
dtformat	A vector of length 2 indicating the format in which `date` and `time` should be interpreted by `chron`.
phase	factor labelling each row for its phase in dive.
type	string indicating whether all points belonging to descent/ascent should be included ("all"), or points shared with bottom phase should be excluded ("srict").
interval	sampling interval in chron units (d).
z	minimum depth differences to use.
zdepth	zero-offset corrected depth m.
vel	velocity in m/s. For doVelCalib: uncalibrated velocities; ignored if `calType` is "none".
dives	3-col `data.frame` with dive id (numeric), activity (factor), and postdive id (numeric).
...	arguments to pass to .descAsc (`type`, `interval`, and `z`).
vdist	vertical distance travelled during ascent or descent.

Details

These functions are not meant to be called directly by the user, as he/she could not care less (right?). This may change in the future.

.getVelCalib extracts the rates of descent and ascent with associated mean velocity during descent and ascent phases, respectively and returns a list that is later manipulated by doVelCalib to calibrate velocity. The velocity used for each rate of depth change corresponds to the velocity read for the last point, assuming that each velocity reading is the average velocity for the last measurement interval.

Value

.getVelCalib: A list with two elements (named "descent" and "ascent"). Each element is a 2-column matrix with rate of depth change in the first column, and velocity in the second, corresponding to the descent phase of each dive.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

diveMove-package   *Time depth recorder analysis*

Description

This package is a collection of functions for visualizing, and analyzing depth and velocity data from time-depth recorders *TDR*s. These can be used to zero-offset correct depth, calibrate velocity, and divide the record into different phases, or time budget. Functions are provided for calculating summary dive statistics for the whole record, or at smaller scales within dives.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

See Also

A vignette with a guide to this package is available by doing 'vignette("diveMove")'. TDR-class, calibrateDepth, calibrateVel, attendance, stampDive.

Examples

```
## read in data and create a TDR object
(sealX <- readTDR(system.file(file.path("data", "sealMK8.csv"),
                              package="diveMove")))
## Not run: plot(sealX)

## detect periods of activity, and calibrate depth, creating
## a 'TDRcalibrate' object
## Not run: (dcalib <- calibrateDepth(sealX))
(dcalib <- calibrateDepth(sealX, offset=3)) # zero-offset correct at 3 m

## plot dive number 100
## Not run:
plot(extractDive(dcalib, 100))
## plot dives 160 to the last one and show dive phases
plot(extractDive(dcalib, 160:max(getDAct(dcalib, "dive.id"))),
     phaseCol=getDPhaseLab(dcalib, 160:max(getDAct(dcalib, "dive.id"))))
## End(Not run)

## calibrate velocity
(vcalib <- calibrateVel(dcalib))

## Obtain dive statistics for all dives detected
dives <- diveStats(vcalib)
## See 'chron' for converting the time columns (1-3) to the desired
## output format
head(dives)

## Attendance table
att <- attendance(vcalib, TRUE)   # ignoring trivial aquatic activities
att <- attendance(vcalib, FALSE)  # taking them into account
## Add trip stamps to each dive
stamps <- stampDive(vcalib)
sumtab <- data.frame(stamps, dives)
```

```
head(sumtab)
```

---

diveStats   *Per-dive statistics*

Description

Calculate dive statistics in TDR records.

Usage

```
diveStats(x)
getDive(x, interval, vel=FALSE)
stampDive(x, ignoreZ=TRUE)
```

Arguments

x	a TDRcalibrate-class object for diveStats and stampDive. a data frame containing a single dive's data.
interval	sampling interval for interpreting x.
vel	logical; should velocity statistics be calculated?
ignoreZ	logical indicating whether trips should be numbered considering all aquatic activities ("W" and "Z") or ignoring "Z" activities.

Details

diveStats calculates various dive statistics based on time and depth for an entire TDR record. getDive obtains these statistics from a single dive, and stampDive stamps each dive with associated trip information.

Value

A data.frame with one row per dive detected (durations are in s, and linear variables in m):

begdesc	a chron object, specifying the start time of each dive.
enddesc	chron object, as begdesc indicating descent's end time.
begasc	chron object, as begdesc indicating the time ascent began.
desctim	descent duration of each dive.
botttim	bottom duration of each dive.
asctim	ascent duration of each dive.
descdist	numeric vector with descent depth.
bottdist	numeric vector with the sum of absolute depth differences while at the bottom of each dive; measure of amount of "wiggling" while at bottom.
ascdist	numeric vector with ascent depth.
desc.tdist	numeric vector with descent total distance, estimated from velocity.
desc.mean.vel	
	numeric vector with descent mean velocity.
desc.angle	numeric vector with descent angle.

bott.tdist	numeric vector with bottom total distance, estimated from velocity.
bott.mean.vel	
	numeric vector with bottom mean velocity.
asc.tdist	numeric vector with ascent total distance, estimated from velocity.
asc.mean.vel	numeric vector with ascent mean velocity.
asc.angle	numeric vector with ascent angle.
divetim	dive duration.
maxdep	numeric vector with maximum depth.
postdive.dur	postdive duration.
postdive.tdist	
	numeric vector with postdive total distance, estimated from velocity.
postdive.mean.vel	
	numeric vector with postdive mean velocity.

The number of columns depends on the value of vel.

stampDive returns a data.frame with trip number, trip type, and start and end times for each dive.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

See Also

detPhase, zoc, TDRcalibrate-class

---

readLocs	*Read comma-delimited file with location data*

Description

Read a comma delimited (*.csv) file with (at least) time, latitude, longitude readings.

Usage

```
readLocs(file, loc.idCol, idCol, dateCol, timeCol=NULL,
         dtformat=c("m/d/y", "h:m:s"), classCol, lonCol, latCol,
         alt.lonCol=NULL, alt.latCol=NULL)
```

Arguments

file	A string indicating the name of the file to read. Provide the entire path if the file is not on the current directory.
loc.idCol	Column number containing location ID.
idCol	Column number containing an identifier for locations belonging to different groups.
dateCol	Column number containing dates, and, optionally, times.
timeCol	Column number containing times.

dtformat	length-2 numeric vector specifying the format (as in chron) in which date and time, respectively, should be read in `file`
lonCol	Column number containing longitude readings.
latCol	Column number containing latitude readings.
classCol	Column number containing the ARGOS rating for each location.
alt.lonCol	Column number containing alternative longitude readings.
alt.latCol	Column number containing alternative latitude readings.

Details

The file must have a header row identifying each field, and all rows must be complete (i.e. have the same number of fields). Field names need not follow any convention.

Value

A data frame.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

| readTDR | *Read comma-delimited file with TDR data* |

Description

Read a comma delimited (*.csv) file containing time-depth recorder (TDR) data from various TDR models. Models supported are MK5, MK7, and MK8 Wildlife Computers instruments. Return a `TDR` or `TDRvel` object. `buildTDR` creates an object of one of these classes from other objects in the session.

Usage

```
readTDR(file, dateCol=1, timeCol=2, depthCol=3, velCol=6,
        subsamp=5, dtformat=c("d/m/y", "h:m:s"))
createTDR(time, depth, vel, dtime, file)
```

Arguments

file	A string indicating the path to the file to read.
dateCol	Column number containing dates, and optionally, times.
timeCol	Column number with times.
depthCol	Column number containing depth readings.
velCol	Column number containing velocity readings.
subsamp	Subsample rows in `file` with subsamp interval, in s.
dtformat	a character vector of length 2, specifying the format of the date and time columns, in that order. See chron for valid format specifications.
time	a chron object
depth	numeric vector with depth readings
vel	optional numeric vector with velocity readings
dtime	sampling interval used in chron units (d)

Details

The file name must contain the adjacent letter "mk" somewhere to be able to identify the TDR model. If the number following these letters is an 8, then a column for velocity readings is expected, in addition to depth.

The file must have a header row identifying each field, and all rows must be complete (i.e. have the same number of fields). Field names need not follow any convention. However, depth and velocity should preferably be given in m, and $m \cdot s^{-1}$ for further analyses.

Value

An object of class 'TDR' or 'TDRvel'.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

Examples

```
readTDR(system.file(file.path("data", "sealMK8.csv"),
                    package="diveMove"))
```

---

rqPlot *Plot of quantile regression for velocity calibrations*

Description

Plot of quantile regression for assessing quality of velocity calibrations

Usage

```
rqPlot(rdepth, vel, rqFit, main="qtRegression",
       xlab="rate of depth change (m/s)",
       ylab="velocity (m/s)",
       colramp=colorRampPalette(c("white", "darkblue")))
```

Arguments

vel	velocity in m/s.
rdepth	numeric vector with rate of depth change.
rqFit	object of class "rq" representing a quantile regression fit of rate of depth change on mean velocity.
main	string; title prefix to include in ouput plot.
xlab, ylab	axis labels.
colramp	function taking an integer n as an argument and returning n colors.

Details

The dashed line in the plot represents a reference indicating a one to one relationship between velocity and rate of depth change. The other line represent the quantile regression fit.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

See Also

doVelCalib, diveStats

Examples

```
## Not run:
plot((sealX <- readTDR(system.file(file.path("data", "sealMK8.csv"),
                                   package="diveMove"))))
## End(Not run)
```

---

sealMK8   *Sample TDR data from a fur seal*

Description

This data set is meant to show the organization a TDR *.csv file must have in order to be used as
input for readTDR.

Format

A comma separated value (csv) file with 69560 TDR readings with the following columns:

date date

time time

depth depth in m

light light level

temperature temperature in C

velocity velocity in m/s

Details

The data is a subset of an entire TDR record, so it is not meant to make any inferences from this
particular individual/deployment.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

Source

Sebastian P. Luque, Christophe Guinet, John P.Y. Arnould

See Also

readTDR

TDRcalibrate-class   *Class "TDRcalibrate" for dive analysis*

Description

This class holds information produced at various stages of dive analysis. Methods are provided for extracting data from each slot.

Details

This is perhaps the most important class in diveMove, as it holds all the information necessary for calculating requested summaries for a TDR.

The `tdr` slot contains the time, zero-offset corrected depth, and possibly calibrated or uncalibrated velocity. See `readTDR` and the accessor function `getTDR` for this slot. Convenient access to each vector in this slot is available through `getTime`, `getDepth`, and `getVeloc`.

The slot gross.activity holds, as a list, a vector (named `phase.id`) numbering each major activity phase found in the record, a factor (named `trip.act`) labelling each row as being on-land, at-sea, or leisure at-sea activity. These two elements are as long as there are rows in `tdr`. This slot also contains two more vectors: one with the beginning time of each phase, and another with the ending time; both represented as `chron` objects. See `detPhase`.

The slot dive.activity contains a data.frame, again with as many rows as those in `tdr`, consisting of three vectors named: `dive.id`, which is an integer vector, sequentially numbering each dive (rows that are not part of a dive are labelled 0), dive.activity is a factor which completes that in `trip.act` above, further identifying rows in the record belonging to a dive. The third vector in dive.activity is an integer vector sequentially numbering each postdive interval (all rows that belong to a dive are labelled 0). See `detDive`, and `getDAct` to access all or any one of these vectors.

dive.phases is a slot corresponding to a factor that labels each row in the record as belonging to a particular phase of a dive. See `labDivePhase`, and `getDPhaseLab` to access this slot.

land.threshold, sea.threshold, dive.threshold, and vel.calib.coefs are each a single number representing parameters used for detecting phases, and calibrating the TDR. Except for the latter, these are mostly for internal use, and hence do not have an accessor function. See `getVelCoef` for accessing vel.calib.coefs.

Objects from the Class

Objects can be created by calls of the form `new("TDRcalibrate", ...)`. The objects of this class contain information necessary to divide the record into sections (e.g. land/water), dive/surface, and different sections within dives. They also contain the parameters used to calibrate velocity and criteria to divide the record into phases.

Slots

tdr: Object of class `"TDR"`, with concurrent time, depth, and possibly velocity (if `"TDRvel"`). See `Details`.

gross.activity: Object of class `"list"`, must be the same as value returned by `detPhase`.

dive.activity: Object of class `"data.frame"`, must be the same as value returned by `detDive`.

dive.phases: Object of class `"factor"`, must be the same as value returned by `labDivePhase`.

land.threshold: Object of class `"numeric"` the temporal criteria used for detecting periods on land that should be considered as at-sea.

sea.threshold: Object of class `"numeric"` the temporal criteria used for detecting periods at-sea that should not be considered as foraging time.

dive.threshold: Object of class `"numeric"` the criteria used for defining a dive.

vel.calib.coefs: Object of class `"numeric"` the intercept and slope derived from the velocity calibration procedure.

Methods

attendance signature(obj = "TDRcalibrate", ignoreZ = "logical"): generates an attendance table for the TDR record; the duration of each dry and wet phase.

getDAct signature(x = "TDRcalibrate", y = "missing"): extracts vectors identifying all readings to a particular dive or postdive number, or a factor identifying all readings to a particular activity.

getDAct signature(x = "TDRcalibrate", y = "character"): as the method for missing y, but selects a particular vector to extract.

getDPhaseLab signature(x = "TDRcalibrate", diveNo = "missing"): extracts a factor identifying all readings to a particular dive phase.

getDPhaseLab signature(x = "TDRcalibrate", diveNo = "numeric"): as the method for missing y, but selects data from a particular dive number to extract.

extractDive signature(obj = "TDRcalibrate", diveNo = "numeric", id = "missing"): extract particular dives.

getGAct signature(x = "TDRcalibrate", y = "missing"): extracts elements that divide the data into major wet and dry activities.

getGAct signature(x = "TDRcalibrate", y = "character"): as the method for missing y, but extracts particular elements.

show signature(object = "TDRcalibrate"): prints informative summary of the data.

getTDR signature(x = "TDRcalibrate"): extracts the TDR object.

getVelCoef signature(x = "TDRcalibrate"): extracts the velocity calibration coefficients.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

See Also

TDR-class for links to other classes in the package

`TDR-class`   *Classes "TDR" and "TDRvel" for representing TDR information*

Description

These classes store information gathered by time-depth recorders.

Details

Since the data to store in objects of these classes usually come from a file, the easiest way to construct such objects is by using the function `readTDR` to retrieve all the necessary information. The methods listed above can thus be used to access all slots.

Objects from the Class

Objects can be created by calls of the form `new("TDR", ...)` and `new("TDRvel", ...)`.

`TDR` objects contain concurrent time and depth readings, as well as a string indicating the file the data originates from, and a number indicating the sampling interval for these data. `TDRvel` extends `TDR` objects containing additional concurrent velocity readings.

Slots

In class *TDR*:

file: Object of class `"character"`, string indicating the file where the data comes from.
dtime: Object of class `"numeric"`, sampling interval in chron units (d).
time: Object of class `"chron"`, time stamp for every reading.
depth: Object of class `"numeric"`, depth (m) readings.

Class *TDRvel* adds:

velocity: Object of class `"numeric"` velocity (m/s) readings.

Methods

as.data.frame `signature(x="TDR")`: Coerce object to data.frame.
as.data.frame `signature(x="TDRvel")`: Coerce object to data.frame.
coerce `signature(from="TDR", to="data.frame")`: Coerce object to data.frame.
coerce `signature(from="TDRvel", to="data.frame")`: Coerce object to data.frame.
getDepth `signature(x = "TDR")`: depth slot accessor.
getDtime `signature(x = "TDR")`: sampling interval accessor.
extractDive `signature(obj = "TDR", diveNo = "numeric", id = "numeric")`: extract particular dives.
getFileName `signature(x="TDR")`: source file name accessor.
plot `signature(x = "TDR", y = "missing")`: interactive graphical display of the data, with zooming and panning capabilities.
plot `signature(x = "TDRvel", y = "missing")`: As the TDR method, but also plots the velocity slot.
show `signature(object = "TDR")`: print an informative summary of the data.
getTime `signature(x = "TDR")`: time slot accessor.
getVeloc `signature(x = "TDRvel")`: velocity accessor for `TDRvel` objects.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

See Also

readTDR, TDRcalibrate-class.

---

doVelCalib   *Calibration of TDR velocity*

Description

Calibrate velocity readings from a TDR, based on the principles outlined in Blackwell et al. (1999).

Usage

```
doVelCalib(rates, vel, calType="pooled", bad=c(0, 0), filename,
          postscript=FALSE, ...)
```

Arguments

rates	two-element list corresponding to descent and ascent phases of dives, respectively. Each element should be a 3-column matrix with dive id, rate of depth change, and mean velocity.
vel	numeric vector with uncalibrated velocities.
calType	string specifying the type of calibration to perform. It should be one of "descent", "ascent", or "pooled".
bad	vector of length 2 indicating values for rate of depth change and mean velocity, respectively, below which data should be excluded to build the calibration curve.
filename	string indicating name of file to use as base name for the output postscript file.
postscript	logical; whether output plot to eps.
...	arguments passed to rqPlot; currently, xlab, ylab, and colramp.

Details

Provide calibrated velocities in a TDR record, using the quantile regression of velocity on rate of depth change, based on principles outlined in Blackwell et al. (1999). Choice of calibrating against pooled, or descentr ascent phases.

The function takes the rates of depth change and velocity, for each phase of the dive separately or combined (based on the value of calType). It subsequently fits a quantile regression through the second percentile of the distribution of velocity conditional on rate of depth change. The calibrated velocity is $v_c = \frac{v_u - a}{b}$, where v_c is the calibrated velocity, v_u is the uncalibrated velocity, and a and b are the intercept and slope of the quantile regression, respectively.

Value

If `calType` is not "none", a list of two elements:

coefficients	numeric vector of length two with the intercept and the slope of the quantile regression defining the calibration curve.
corrVel	numeric vector as long as `vel` with the calibrated velocities.

A plot (possibly via [postscript](), depending on the value of postscript argument) of the calibration lines for all possible cases: "descent", "ascent", and "pooled", is created as a side effect.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩

References

Blackwell, S. (1999) A method for calibrating swim-speed recorders. Marine Mammal Science **15(3)**: 894-905.

See Also

[TDRcalibrate-class](), [rqPlot]()

---

zoc	*Interactive zero-offset correction of TDR data*

Description

Correct zero-offset in TDR records, with the aid of a graphical user interface (GUI), allowing for dynamic selection of offset and multiple time windows to perform the adjustment.

Usage

```
zoc(time, depth, offset)
plotDive(time, depth, vel=NULL, xlim=NULL, phaseCol=NULL)
```

Arguments

time	chron object with date and time.
depth	numeric vector with depth in m.
offset	known amount of meters for zero-offset correcting depth throughout the entire TDR record.
vel	numeric vector with velocity in m/s.
xlim	vector of length 2, with lower and upper limits of time to be plotted.
phaseCol	factor dividing rows into sections.

Details

These functions are used primarily to correct, visually, drifts in the pressure transducer of TDR records. `zoc` calls `plotDive`, which plots depth and, optionally, velocity vs. time with the possibility zooming in and out on time, changing maximum depths displayed, and panning through time. The option to zero-offset correct sections of the record gathers x and y coordinates for two points, obtained by clicking on the plot region. The first point clicked indicates the offset and beginning time of section to correct, and the second one indicates the ending time of the section to correct. Multiple sections of the record can be corrected in this manner, by panning through the time and repeating the procedure. In case there's overlap between zero offset corrected windows, the last one prevails.

Once the whole record has been zero-offset corrected, remaining points with depth values lower than zero, are turned into zeroes, as these are assumed to be values at the surface.

Value

`zoc` returns a numeric vector, as long as `depth` of zero-offset corrected depths.

`plotDive` returns a list with as many components as sections of the record that were zero-offset corrected, each consisting of two further lists with the same components as those returned by `locator`.

Author(s)

Sebastian P. Luque ⟨spluque@gmail.com⟩, with many ideas from CRAN package sfsmisc.

See Also

`detDive`

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