Analyzing shape, accuracy, and precison of shooting results with `shotGroups`

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Contents

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1 Introduction

The `shotGroups` package adds functionality to the open source statistical environment R (R Development Core Team, 2014a).[1] It provides functions to read in, plot, statistically describe, analyze, and compare shooting data with respect to group shape, precision, and accuracy. This includes graphical methods, descriptive statistics, and inference tests using standard, but also nonparametric and robust statistical techniques. The data can be imported from files produced by OnTarget PC and OnTarget TDS (Block, 2014), or from custom data files in text format with a similar structure.

The package includes limited support for the analysis of three-dimensional data (see sections 3.2.1, 3.2.2),

Use `help(package="shotGroups")` for a list of all functions and links to the detailed help pages with information on options, usage and output.

2 Analyzing bullet hole data

Analyzing shot groups usually takes the following steps:

- Read in data (section 2.1)
- Perform either a comprehensive numerical as well as graphical analysis of a group's shape, location (accuracy), and spread (precision) with `analyzeGroup()` (section 2.2) ...
- ...or analyze these aspects of a group separately with `groupShape()` (section 2.3), `groupSpread()` (section 2.4), `groupLocation()` (section 2.5)
- Numerically and visually compare different groups in terms of their shape, location (accuracy), and spread (precision) with `compareGroups()` (section 2.6)
- Use additional utility functions (section 3) to individually explore different aspects of a given group

Grubbs (1964b) and `http://ballistipedia.com/` are good sources for statistical methods for analyzing shot groups.

2.1 Reading in data

To import data into R, it should be saved as a text file with the following format:

- The file should have one row for each shot, and one column for each coordinate as well as for any other variable such as distance to target, point-of-aim coordinates.
- Columns should be separated by commas, tabs or other whitespace. This type of text file can be exported from OnTarget PC/TDS, or from a spreadsheet application like Excel or Calc.
- The file needs a header in the first line giving the variable names, and should contain at least the coordinates of points of impact, either with variable names `Point.X`, `Point.Y` or just `X`, `Y`.

[1] For an introduction to R, see Dalgaard (2008), TryR (`http://tryr.codeschool.com/`) or Quick-R (`http://www.statmethods.net/`).

- For several analysis functions, the following additional variables are useful: `Group` (group number), `Distance` (distance to target), and `Aim.X`, `Aim.Y` (point of aim). If these variables are missing, default values are assumed with a warning.
- Note that R is case sensitive, so the aforementioned variable names must match exactly.
- If you have output files from OnTarget PC/TDS, you can read multiple files with `readDataOT1()` (for OnTarget PC v1.*), or with `readDataOT2()` (for OnTarget PC v2.* and OnTarget TDS v3.*).
- If you have other whitespace or comma-separated text files with the structure outlined above, you can read multiple files with `readDataMisc()`. For three-dimensional data, this function also recognizes variables `Point.Z` or `Z` and `Aim.Z`.
- If your data is saved in some other text file format, consult the help for `read.table()` or the R import/export manual (R Development Core Team, 2014b).

```
library(shotGroups, verbose=FALSE)       # load shotGroups package

## read text files and save to data frame
## not run, we later use data frame provided in package instead
DFgroups <- readDataMisc(fPath="c:/path/to/files",
                         fNames=c("series1.dat", "series2.dat"))
```

By default, OnTarget's "Export Point Data" places the origin of the coordinate system in the top-left corner. This can be taken into account by correctly setting the option `xyTopLeft` in functions `analyzeGroup()` (section 2.2), `compareGroups` (section 2.6), and `drawGroup()` (section 3.3). In OnTarget TDS, the orientation of the y-axis can be changed by checking the box "Tools → Options → Options tab → Data Export → Invert Y-Axis on Export". If groups appear to be upside-down, `xyTopLeft` is the setting to change.

When analyzing different aspects of a group separately using `groupShape()` (section 2.3), `groupSpread()` (section 2.4), and `groupLocation()` (section 2.5), the scatterplots will be upside-down if the default option of OnTarget was used.

2.2 Performing a combined analysis

`analyzeGroup()`: This function is a convencience wrapper for the functions presented in sections 2.3, 2.4, and 2.5. It analyzes a group's shape, precision, and accuracy in one go, and collects the results.

```
library(shotGroups, verbose=FALSE)       # load shotGroups package
analyzeGroup(DFtalon, conversion="m2mm")

## output not shown, see following sections for results
```

2.3 Analyzing group shape

`groupShape()`: Assess (multivariate) normality, identify outliers and get a sense for the shape of the bivariate distribution.

Reported statistical parameters and tests:

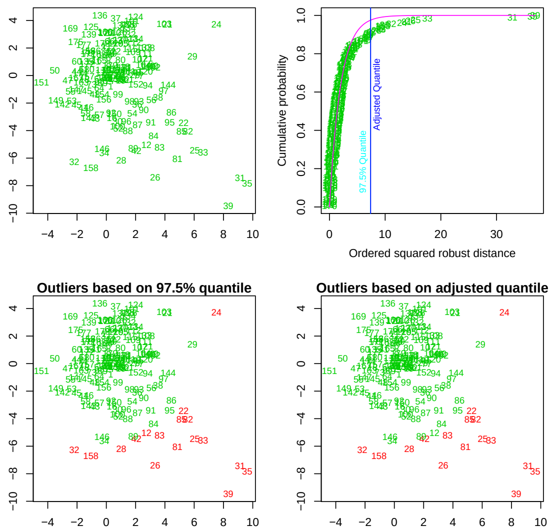
- Correlation matrix including a robust estimate using the MCD method (from package `robustbase`; Rousseeuw et al., 2014)
- Outlier identification: Either using squared robust Mahalanobis distances and adjusted quantiles from the χ^2-distribution, or using robust principal components analysis (PCA) with options to tune the sensitivity (from package `mvoutlier`; Filzmoser & Gschwandtner, 2014)
- Shapiro-Wilk normality tests for the distribution of x- and y-coordinates. For more than 5000 observations, the drop-in Kolmogorov-Smirnov-test is reported instead.
- Energy test for bivariate normality of (x, y)-coordinates (from package `energy`; Rizzo & Szekely, 2014)

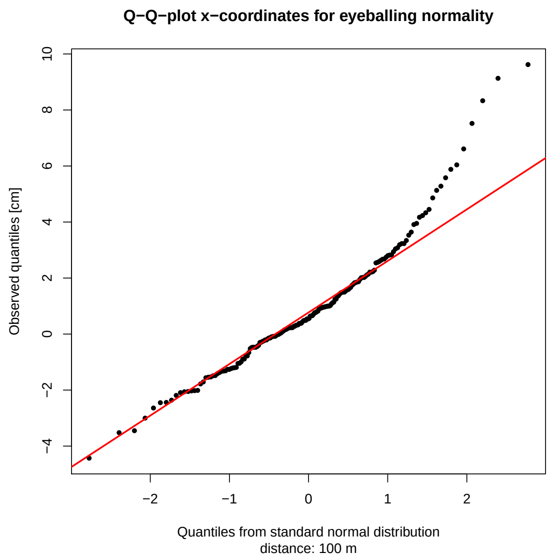
Plots:

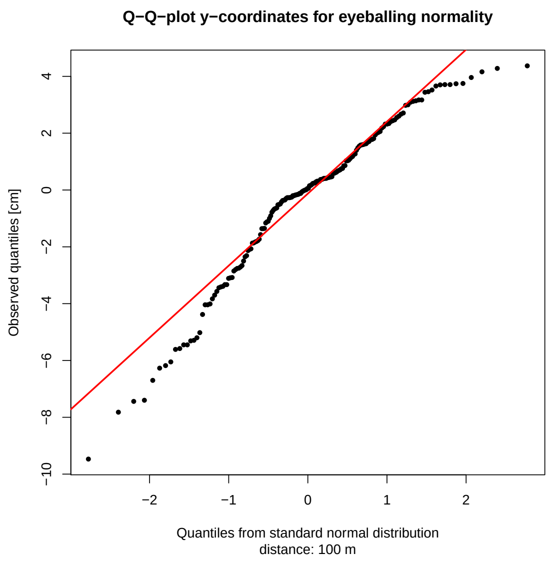
- Combined plot for multivariate outlier identification using squared robust Mahalanobis distances and adjusted quantiles from the χ^2-distribution (from package `mvoutlier`)
- χ^2 Q-Q-plot for eyeballing multivariate normality of (x, y)-coordinates
- Heatmap of a nonparametric 2D-kernel density estimate for the (x, y)-coordinates (from package `KernSmooth`; Wand, 2013) together with robust group center and robust error ellipse
- Q-Q-plots for eyeballing normality of x- and y-coordinates
- Histogram of x- and y-coordinates including a fitted normal distribution as well as a nonparametric kernel density estimate

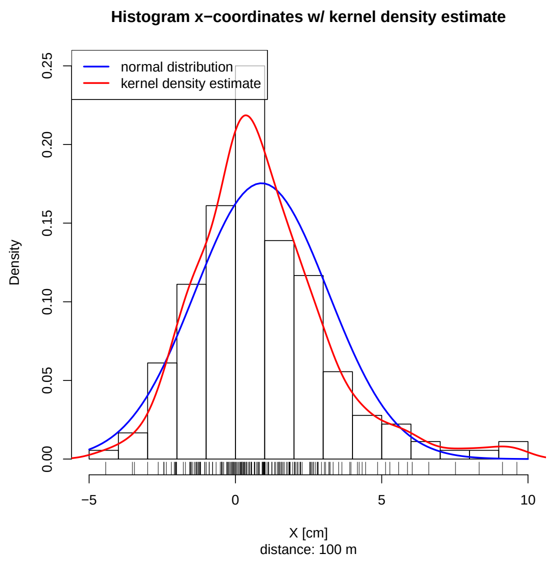
```
library(shotGroups, verbose=FALSE)       # load shotGroups package
groupShape(DFtalon, bandW=0.4, outlier="mcd")

$corXY
        X       Y
X  1.0000 -0.2931
Y -0.2931  1.0000

$corXYrob
        X       Y
X 1.00000 0.09767
Y 0.09767 1.00000

$Outliers
 [1]  22  24  25  26  28  31  32  33  35  39  42  81  82  83  85 158

$ShapiroX

Shapiro-Wilk normality test

data:  X
```

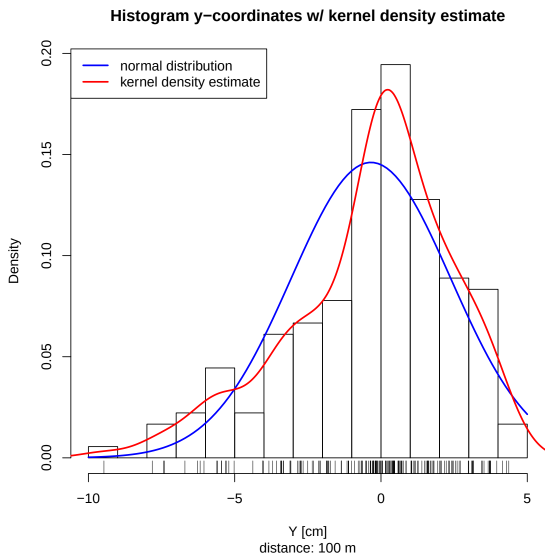
```
W = 0.9471, p-value = 3.105e-06


$ShapiroY

Shapiro-Wilk normality test

data:  Y
W = 0.9552, p-value = 1.769e-05


$multNorm

Energy test of multivariate normality: estimated parameters

data:  x, sample size 180, dimension 2, replicates 1499
E-statistic = 3.74, p-value < 2.2e-16
```

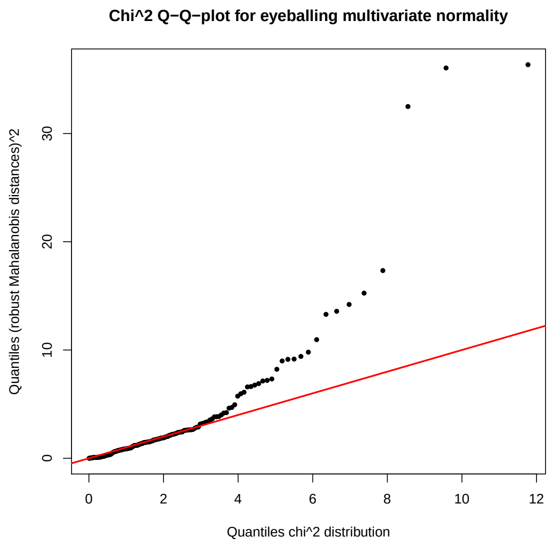


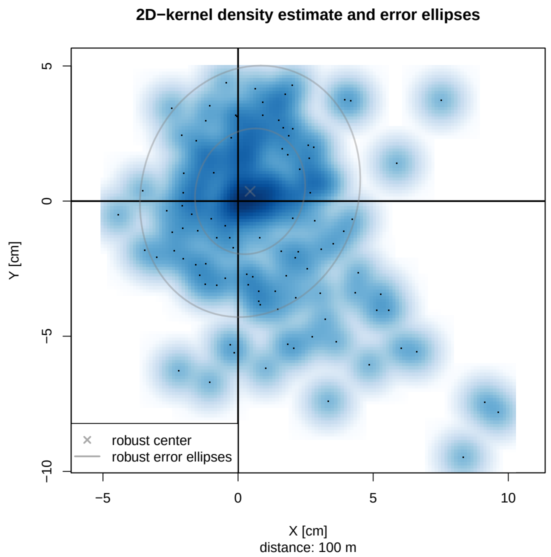



Q−Q−plot y−coordinates for eyeballing normality
Observed quantiles [cm]
Quantiles from standard normal distribution
distance: 100 m


Histogram x−coordinates w/ kernel density estimate
normal distribution
kernel density estimate
Density
X [cm]
distance: 100 m


Histogram y−coordinates w/ kernel density estimate
normal distribution
kernel density estimate
Density
Y [cm]
distance: 100 m


Chi^2 Q−Q−plot for eyeballing multivariate normality
Quantiles (robust Mahalanobis distances)^2
Quantiles chi^2 distribution



2.4 Analyzing group spread – precision

`groupSpread()`: Assess precision using empirical and parametric spread measures with confidence intervals. Where possible, also use the MCD method for a robust estimate of the covariance matrix (from package `robustbase`). Bootstrap confidence intervals are from package `boot` (Canty & Ripley, 2013) with 1499 replications.

Reported statistical parameters and tests:

- (Robust) Standard deviations of x- and y-coordinates together with parametric and bootstrap confidence intervals (in original measurement units, MOA, SMOA, milrad)
- (Robust) Covariance matrix of (x, y)-coordinates
- Empirical mean and median radius as well as estimated Rayleigh precision parameter σ, estimated Rayleigh radial standard deviation RSD $= \sigma\sqrt{\frac{4-\pi}{2}}$, and estimated Rayleigh mean radius MR $= \sigma\sqrt{\frac{\pi}{2}}$ together with parametric and bootstrap confidence intervals for σ, RSD, and MR (in original measurement units, MOA, SMOA, milrad)
- Maximum pairwise distance (center-to-center, = maximum spread, in original measurement units, MOA, SMOA, milrad)
- Width and height of bounding box with diagonal and figure of merit as well as of the (oriented) minimum-area bounding box (in original measurement units, MOA, SMOA, milrad)
- Radius for the minimum enclosing circle (in original measurement units, MOA, SMOA, milrad)
- Length of semi-major and semi-minor axis of the (robust) confidence ellipse (in original measurement units, MOA, SMOA, milrad)
- Aspect ratio $\sqrt{\kappa}$ (with condition index κ) and flattening $1 - \frac{1}{\sqrt{\kappa}}$ of the (robust) confidence ellipse as well as the trace and determinant of the covariance matrix
- Estimate for the circular error probable CEP (see section 3.2.1; in original measurement

units, MOA, SMOA, milrad)

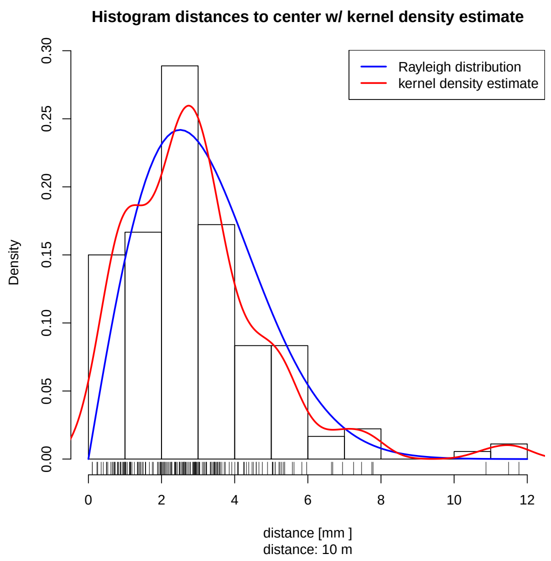
Plots:

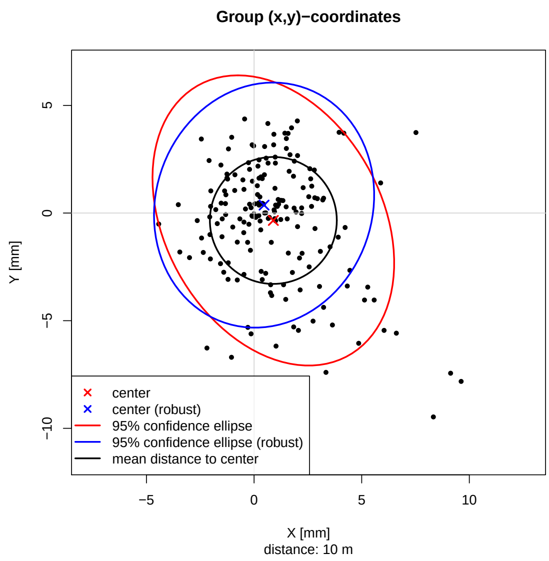
- Scatterplot of the (x, y)-coordinates together with group center, circle with average distance to center, and (robust) confidence ellipse
- Scatterplot of the (x, y)-coordinates together with the bounding box, minimum-area bounding box, minimum enclosing circle, and maximum group spread
- Histogram of distances to group center including a Rayleigh fit and a nonparametric kernel density estimate

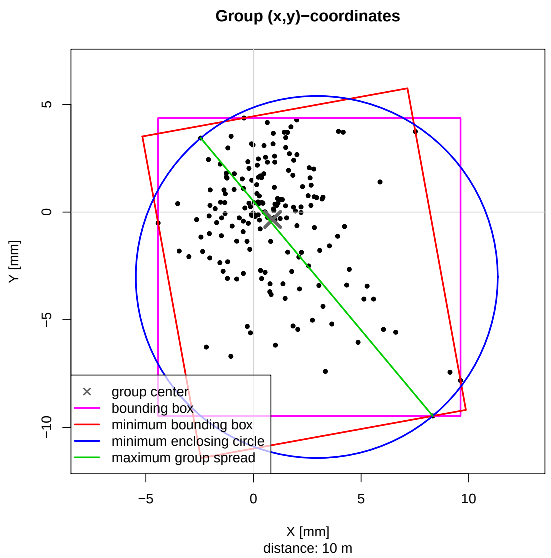
```
library(shotGroups, verbose=FALSE)       # load shotGroups package
groupSpread(DFtalon, CEPtype=c("CorrNormal", "GrubbsPatnaik", "Rayleigh"),
            level=0.95, bootCI="basic", dstTarget=10, conversion="m2mm")

$sdXY
            X      Y
unit   2.2746 2.7308
MOA    0.7819 0.9388
SMOA   0.8188 0.9831
milrad 0.2275 0.2731

$sdXci
        sdX (   sdX ) sdX basic ( sdX basic )
unit   2.0614 2.5374       1.9558       2.6045
MOA    0.7087 0.8723       0.6723       0.8954
SMOA   0.7421 0.9134       0.7041       0.9376
milrad 0.2061 0.2537       0.1956       0.2604

$sdYci
        sdY (   sdY ) sdY basic ( sdY basic )
unit   2.4749 3.0463       2.4332       3.0615
MOA    0.8508 1.0472       0.8365       1.0525
SMOA   0.8909 1.0967       0.8759       1.1022
milrad 0.2475 0.3046       0.2433       0.3062

$sdXYrob
            X      Y
unit   2.0721 2.3063
MOA    0.7123 0.7928
SMOA   0.7460 0.8303
milrad 0.2072 0.2306

$covXY
       X      Y
X  5.174 -1.820
Y -1.820  7.457
```

```
$covXYrob
       X      Y
X 4.2935 0.3929
Y 0.3929 5.3188

$distToCtr
         mean median  sigma    RSD     MR
unit   2.9486 2.6696 2.5078 1.6430 3.1431
MOA    1.0137 0.9178 0.8621 0.5648 1.0805
SMOA   1.0615 0.9611 0.9028 0.5915 1.1315
milrad 0.2949 0.2670 0.2508 0.1643 0.3143

$sigmaCI
       sigma ( sigma ) sigma basic ( sigma basic )
unit    2.3433  2.7136        2.2385        2.8002
MOA     0.8056  0.9329        0.7695        0.9626
SMOA    0.8436  0.9769        0.8059        1.0081
milrad  0.2343  0.2714        0.2239        0.2800

$RSDci
        RSD (  RSD ) RSD basic ( RSD basic )
unit   1.5352 1.7778      1.4665      1.8345
MOA    0.5278 0.6112      0.5042      0.6307
SMOA   0.5527 0.6400      0.5279      0.6604
milrad 0.1535 0.1778      0.1467      0.1835

$MRci
         MR (   MR ) MR basic ( MR basic )
unit   2.9369 3.4010     2.8056      3.510
MOA    1.0096 1.1692     0.9645      1.206
SMOA   1.0573 1.2244     1.0100      1.263
milrad 0.2937 0.3401     0.2806      0.351

$maxPairDist
  unit    MOA   SMOA milrad
16.819  5.782  6.055  1.682

$groupRect
        width height    FoM   diag
unit   14.050 13.840 13.945 19.722
MOA     4.830  4.758  4.794  6.780
SMOA    5.058  4.982  5.020  7.100
milrad  1.405  1.384  1.394  1.972

$groupRectMin
        width height    FoM   diag
```

```
unit   15.185 12.517 13.851 19.679
MOA     5.220  4.303  4.762  6.765
SMOA    5.466  4.506  4.986  7.084
milrad  1.518  1.252  1.385  1.968

$minCircleRad
  unit    MOA   SMOA milrad
8.4095 2.8910 3.0274 0.8409

$confEll
       semi-major semi-minor
unit       7.1814     5.0386
MOA        2.4688     1.7321
SMOA       2.5853     1.8139
milrad     0.7181     0.5039

$confEllRob
       semi-major semi-minor
unit       5.8072     4.9512
MOA        1.9964     1.7021
SMOA       2.0906     1.7824
milrad     0.5807     0.4951

$confEllShape
aspectRatio  flattening       trace         det
     1.4253      0.2984     12.6311     35.2687

$confEllShapeRob
aspectRatio  flattening       trace         det
     1.1729      0.1474      9.5585     22.2700

$CEP
       CorrNormal GrubbsPatnaik Rayleigh
unit       6.2469        6.2722   6.1385
MOA        2.1475        2.1562   2.1103
SMOA       2.2489        2.2580   2.2099
milrad     0.6247        0.6272   0.6139
```







2.5 Analyzing group location – accuracy

`groupLocation()`: Assess accuracy of a group using empirical and parametric measures. Where possible, also use the MCD method for a robust estimate of the covariance matrix (from package `robustbase`). Bootstrap confidence intervals are from package `boot` with 1499 replications.

Reported statistical parameters and tests:

- (x, y)-offset of (robust) group center relative to point of aim
- Distance from (robust) group center to point of aim (in original measurement units, MOA, SMOA, milrad)
- Hotelling's T^2-test result for equality of the true group center with point of aim
- Parametric and bootstrap confidence intervals for the true center's x- and y-coordinate

Plots:

- Scatterplot of the (x, y)-coordinates together with (robust) group center.

```
library(shotGroups, verbose=FALSE)       # load shotGroups package
groupLocation(DFtalon, dstTarget=10, conversion="m2cm",
              level=0.95, plots=FALSE, bootCI="basic")

$ctr
      X       Y
 0.8947 -0.3432

$ctrRob
     X      Y
0.4646 0.3696

$distPOA
  unit    MOA   SMOA milrad
0.9583 3.2943 3.4498 0.9583

$distPOArob
  unit    MOA   SMOA milrad
0.5937 2.0411 2.1374 0.5937

$Hotelling
Analysis of Variance Table

             Df Hotelling-Lawley approx F num Df den Df  Pr(>F)
(Intercept)   1            0.156     13.9      2    178 2.5e-06
Residuals   179

$ctrXci
         x (   x )
t     0.5602 1.229
basic 0.5646 1.235

$ctrYci
          y (     y )
t     -0.7448 0.05849
basic -0.7199 0.04987
```

2.6 Comparing groups

`compareGroups()`: Compare two or more groups with regard to their precision and accuracy using empirical measures and statistical tests.

`compareGroups()` requires that the data includes a variable `Series` that identifies shot groups. OnTarget PC/TDS' variable `Group` identifies groups just within one file, `Series` should number groups also across different original files. When you read in data with `readDataOT1()`, `Series` is added automatically (same for `readDataOT2()` and `readDataMisc()`). For data from just one file, you can otherwise copy variable `Group` to `Series` in a data frame called `shots` with

```
shots$Series <- shots$Group
```

Reported statistical parameters and tests:

- Group center offset from the respective point of aim
- Distances from group centers to their respective point of aim (in original measurement units, MOA, SMOA, milrad)
- MANOVA result from testing equality of group center offset from the respective point of aim
- Group correlation matrices for the (x, y)-coordinates
- Group standard deviations of the x- and y-coordinates including parametric 95%-confidence intervals (in original measurement units, MOA, SMOA, milrad)
- Average distances from points to their respective group center (in original measurement units, MOA, SMOA, milrad)
- Maximum pairwise distance between points for each group (center-to-center, = maximum spread, in original measurement units, MOA, SMOA, milrad)
- Figure of merit FoM and diagonal of the (oriented) minimum-area bounding box for each group (in original measurement units, MOA, SMOA, milrad)
- Radius of the minimum enclosing circle for each group (in original measurement units, MOA, SMOA, milrad)
- Estimate for the 50% circular error probable (CEP) in each group (see section 3.2.1; in original measurement units, MOA, SMOA, milrad)
- Ansari-Bradley-test results from testing equality of group variances for x- and y-coordinates – when two groups are compared. With more than two groups, the Fligner-Killeen-test is used
- Wilcoxon-Rank-Sum-test (= Mann-Whitney-U-test) result from testing equality of average point distances to their respective group center – when two groups are compared. With more than two groups, the Kruskal-Wallis-test is used

The Ansari-Bradley-, Fligner-Killeen-, Wilcoxon-Rank-Sum-, and Kruskal-Wallis-tests are implemented as permutation tests using the `coin` package (Hothorn, Hornik, van de Wiel, & Zeileis, 2008). The tests for two groups (Ansari-Bradley, Wilcoxon) use the exact permutation distribution, the tests for more than two groups (Fligner-Killeen, Kruskal-Wallis) use the approximate permutation distribution with 9999 random permutations.

Plots:

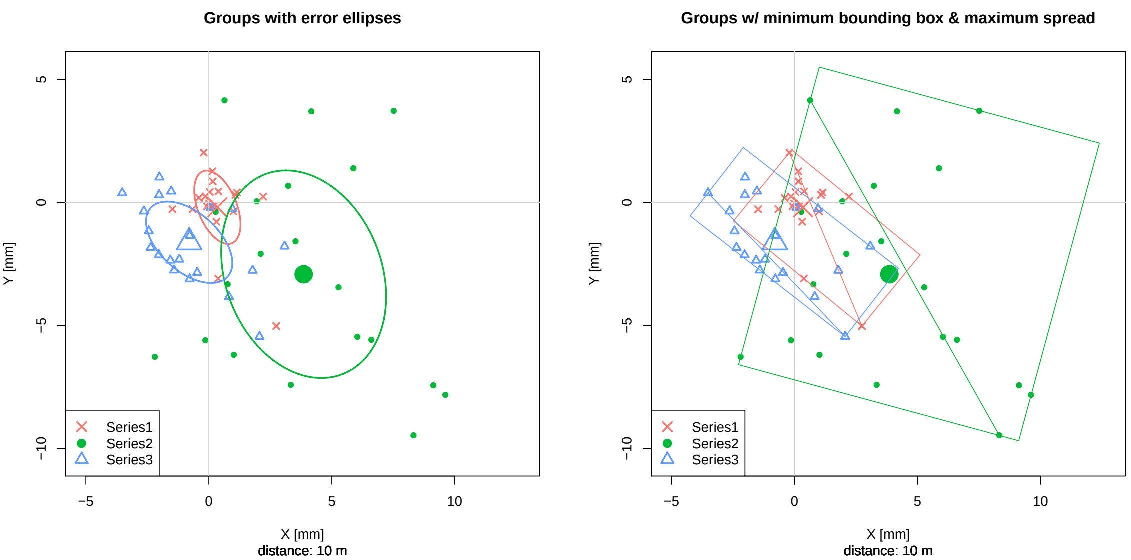
- Scatterplot showing all groups as well as their respective center and 50%-confidence ellipse
- Scatterplot showing all groups as well as their respective (minimum) bounding box and maximum group spread
- Scatterplot showing all groups as well as their respective minimum enclosing circle and circle with average distance to center

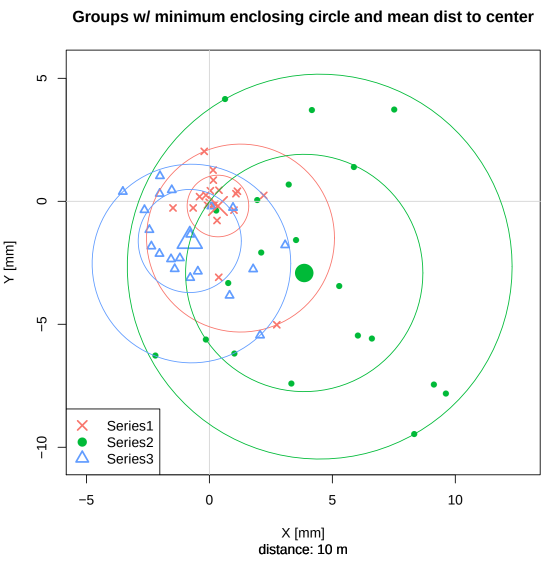
```r
library(shotGroups, verbose=FALSE)       # load shotGroups package

## only use first 3 groups of DFtalon
DFsub <- subset(DFtalon, Series %in% 1:3)
compareGroups(DFsub, conversion="m2mm")


$ctr
  Series1 Series2 Series3
X  0.3475   3.856 -0.7985
Y -0.1910  -2.913 -1.6140

$distPOA
       Series1 Series2 Series3
unit   0.39653  4.8329  1.8007
MOA    0.13632  1.6614  0.6190
SMOA   0.14275  1.7399  0.6483
milrad 0.03965  0.4833  0.1801

$MANOVA
Analysis of Variance Table

            Df Wilks approx F num Df den Df  Pr(>F)
(Intercept)  1 0.676     13.4      2     56 1.7e-05
Series       2 0.504     11.4      4    112 7.9e-08
Residuals   57

$corXY
$corXY$Series1
        X       Y
X  1.0000 -0.4632
Y -0.4632  1.0000

$corXY$Series2
        X       Y
X  1.0000 -0.2143
Y -0.2143  1.0000

$corXY$Series3
        X       Y
X  1.0000 -0.5081
Y -0.5081  1.0000


$sdXY
$sdXY$Series1
             X      Y
```

```
unit   0.94037 1.4912
MOA    0.32327 0.5126
SMOA   0.33853 0.5368
milrad 0.09404 0.1491

$sdXY$Series2
            X     Y
unit   3.3539 4.220
MOA    1.1530 1.451
SMOA   1.2074 1.519
milrad 0.3354 0.422

$sdXY$Series3
            X      Y
unit   1.7549 1.6556
MOA    0.6033 0.5691
SMOA   0.6318 0.5960
milrad 0.1755 0.1656


$sdXYci
$sdXYci$Series1
         sdX (  sdX )  sdY (  sdY )
unit   0.71514 1.3735 1.1340 2.1780
MOA    0.24585 0.4722 0.3898 0.7487
SMOA   0.25745 0.4945 0.4082 0.7841
milrad 0.07151 0.1373 0.1134 0.2178

$sdXYci$Series2
        sdX (  sdX )  sdY (  sdY )
unit   2.5506 4.8986 3.2094 6.1638
MOA    0.8768 1.6840 1.1033 2.1190
SMOA   0.9182 1.7635 1.1554 2.2190
milrad 0.2551 0.4899 0.3209 0.6164

$sdXYci$Series3
        sdX (  sdX )  sdY (  sdY )
unit   1.3346 2.5631 1.2591 2.4181
MOA    0.4588 0.8811 0.4328 0.8313
SMOA   0.4804 0.9227 0.4533 0.8705
milrad 0.1335 0.2563 0.1259 0.2418


$meanDistToCtr
       Series1 Series2 Series3
unit    1.2526  4.8246  2.0961
```

```
MOA     0.4306  1.6586  0.7206
SMOA    0.4509  1.7368  0.7546
milrad  0.1253  0.4825  0.2096

$maxPairDist
       Series1 Series2 Series3
unit    7.6423  15.650  8.0773
MOA     2.6272   5.380  2.7768
SMOA    2.7512   5.634  2.9078
milrad  0.7642   1.565  0.8077

$bbFoM
       Series1 Series2 Series3
unit    5.2415  12.170  5.7565
MOA     1.8019   4.184  1.9790
SMOA    1.8869   4.381  2.0724
milrad  0.5241   1.217  0.5757

$bbDiag
       Series1 Series2 Series3
unit    7.7121  17.219  8.7324
MOA     2.6512   5.920  3.0020
SMOA    2.7764   6.199  3.1437
milrad  0.7712   1.722  0.8732

$minCircleRad
       Series1 Series2 Series3
unit    3.8212  7.8248  4.0386
MOA     1.3136  2.6900  1.3884
SMOA    1.3756  2.8169  1.4539
milrad  0.3821  0.7825  0.4039

$CEP
       Series1 Series2 Series3
unit    1.3724  4.4169  1.9169
MOA     0.4718  1.5184  0.6590
SMOA    0.4940  1.5901  0.6901
milrad  0.1372  0.4417  0.1917

$FlignerX

Approximative Fligner-Killeen Test

data:  X by Series (1, 2, 3)
chi-squared = 18.23, p-value < 2.2e-16
```

```
$FlignerY

Approximative Fligner-Killeen Test

data:  Y by Series (1, 2, 3)
chi-squared = 21.42, p-value < 2.2e-16


$Kruskal

Approximative Kruskal-Wallis Test

data:  dstCtr by Series (1, 2, 3)
chi-squared = 15.34, p-value = 2e-04
```





3 Additional functionality

The `shotGroups` package also provides a number of utility functions that can be used separately to …

- calculate individual descriptive precision measures (section 3.1)
- estimate hit probabilities: either get the region that is expected to contain a certain fraction of shots, or get the estimated fraction of shots expected to be within a given region (section 3.2)
- plot a group to scale on a target background and add precision indicators (section 3.3)
- simulate the ring count for a given group, bullet diameter, and target type (section 3.4)
- convert between absolute and angular size units MOA, SMOA, and milrad (section 3.5)
- try an analysis on collections of empirical data included in the package (section 3.6)

3.1 Descriptive precision measures

The following functions can be used to calculate precision measures that summarize some feature of the group's geometry. Section 3.3 illustrates how to add these precision indicators to a plot of the group.

- `getBoundingBox()`: Calculates the vertices, length of diagonal, and figure of merit (FoM) of the axis-aligned bounding box. This is the smallest rectangle that contains all points (bullet hole centers), and has edges parallel to the x- and y-axes.
- `getMinBBox()`: Calculates the vertices, length of diagonal, and figure of merit (FoM) of the minimum-area bounding box. This is the smallest, possibly oriented rectangle that contains all points (bullet hole centers). Uses the rotating calipers algorithm (Toussaint, 1983).
- `getMinCircle()`: Calculates center and radius of the minimum enclosing circle. This is

the smallest circle that contains all points (bullet hole centers). Uses the Skyum algorithm (Skyum, 1991).

- `getDistToCtr()`: Calculates the distances of a set of points to their center. The mean or median can then be taken as a precision measure.
- `getMaxPairDist()`: Calculates the maximum of all pairwise distances between points.

```
library(shotGroups, verbose=FALSE)        # load shotGroups package
getBoundingBox(DFtalon)                   # axis-aligned bounding box

$pts
  xleft ybottom  xright    ytop
  -4.43   -4.37    9.62    9.47

$width
[1] 14.05

$height
[1] 13.84

$FoM
[1] 13.95

$diag
[1] 19.72

getMinBBox(DFtalon)                       # minimum-area bounding box

$pts
          X      Y
[1,] -2.447 11.428
[2,] -5.161 -3.512
[3,]  7.155 -5.750
[4,]  9.869  9.190

$width
[1] 15.18

$height
[1] 12.52

$FoM
[1] 13.85

$diag
[1] 19.68
```

```
$angle
   Y
79.7

getMinCircle(DFtalon)                     # minimum enclosing circle

$ctr
[1] 2.940 3.015

$rad
[1] 8.409

getMaxPairDist(DFtalon)                   # maximum pairwise distance

$d
[1] 16.82

$idx
[1] 169  39
```

3.2 Estimating hit probability

Beyond calculating decriptive/geometric precision measures, `shotGroups` also includes functions that provide inferential statistics to estimate hit probabilities.

- Section 3.2.1 shows how to estimate the circular, spherical or elliptical region that is expected to contain a given fraction of shots.
- Section 3.2.2 describes how to estimate the fraction of shots expected to be within a given distance to the true group center.
- Section 3.2.3 covers the extrapolation of hit probabilities to different distances other than the one a group was actually shot at.

3.2.1 Region for a given hit probability: CEP, SEP and confidence ellipse

The following functions estimate the region that is expected to contain a given fraction of shots (bullet hole centers) under different assumptions. The given fraction of shots is the same as the probability for one shot to lie within the calculated region. The functions can use the MCD method for a robust estimate of the group center and covariance matrix (from package `robustbase`). See section 3.2.4 for more references to relevant literature.

- `getCEP()`: Calculates estimates for the Circular Error Probable CEP. For three-dimensional data, the Spherical Error Probable SEP is returned. The CEP/SEP estimate is the radius of the circle/sphere around the true mean μ of the distribution that is expected to cover a certain fraction of points. If systematic accuracy bias is ignored, μ is assumed to coincide with the group center. If systematic accuracy bias is taken into account, μ is assumed to be the point of aim, possibly offset from the group center. The following estimates are available:

- `CorrNormal`: If systematic accuracy bias is ignored, this estimate is based on the closed-form solution for the distribution of radial error in the bivariate normal distribution re-written in polar coordinates (radius and angle; Hoyt, 1947; Paris, 2009a, 2009b). Shot coordinates may be correlated and have unequal variances. If systematic accuracy bias is taken into account, package `CompQuadForm` (Duchesne & Lafaye de Micheaux, 2010) is used to calculate the cdf of radial error using numerical integration of the multivariate normal distribution over an offset disc (DiDonato & Jarnagin, 1961a; Evans, Govindarajulu, & Barthoulot, 1985) or sphere (DiDonato, 1988). The quantile function uses numerical root finding to get the inverse cdf. The `CorrNormal` estimate is available for all proability levels and generalizes to three dimensions.
- `GrubbsPearson`: The Grubbs-Pearson estimate (Grubbs, 1964a) is based on the Pearson three-moment central χ^2-approximation (Imhof, 1961; Pearson, 1959) of the cumulative distribution function of radial error in bivariate normal variables. Shot coordinates may be correlated and have unequal variances. The eigenvalues of the covariance matrix of coordinates are used as variance estimates since they are the variances of the principal components (the PCA-rotated = decorrelated data). For probabilities ≥ 0.25, the approximation is very close to the true cumulative distribution function (cdf) used in `CorrNormal` – but easier to calculate. For probabilities < 0.25 and some distribution shapes, the approximation can diverge from the true cdf. The Grubbs-Pearson estimate is available for all proability levels, and generalizes to three dimensions.
- `GrubbsPatnaik`: The Grubbs-Patnaik estimate (Grubbs, 1964a) differs from the Grubbs-Pearson estimate insofar as it is based on the Patnaik (1949) two-moment central χ^2-approximation of the true cumulative distribution function of radial error. For probabilities < 0.5 and some distribution shapes, the approximation can diverge from the true cdf.
- `GrubbsLiu`: The Grubbs-Liu estimate was not proposed by Grubbs but follows the same principle as his original estimates. It differs from them insofar as it is based on the Liu, Tang, and Zhang (2009) four-moment non-central χ^2-approximation of the true cumulative distribution function of radial error. For `accuracy=FALSE`, it is identical to `GrubbsPearson`.
- `Rayleigh`: This estimate uses the Rayleigh distribution with a bias-corrected estimate of its scale parameter σ (H. P. Singh, 1992). The Rayleigh distribution assumes uncorrelated multivariate normal shot coordinates with equal variances σ^2. Numerical simulations suggest reasonable coverage for aspect ratios of the error ellipse not exceeding 4, and for quantiles in the range of $[0.5, 0.9]$. The Rayleigh estimate is available for all proability levels, and generalizes to three dimensions.
- `Ethridge`: The Ethridge estimate (Ethridge, 1983) is not based on the assumption of multivariate normality of shot coordinates but uses a robust unbiased estimator for the median radius (Hogg, 1967). The Ethridge estimate is also documented in Puhek (1992).[2] This estimate can only be reported for probability 0.5 but generalizes

[2] Note that the formula for the Hogg weighted location estimate is wrong in Puhek (1992); Tongue (1993);

to three dimensions.

  - `RAND`: The modified RAND R-234 estimate (RAND Corporation, 1952) is a weighted sum of the square root of the eigenvalues of the covariance matrix, that is of the standard deviations of the two principal components. The bias correction with `accuracy=TRUE` is based on a cubic regression fit to tabulated data (Pesapane & Irvine, 1977; Puhek, 1992). This estimate can only be reported for probability 0.5 and does not generalize to three dimensions.

- `getConfEll()`: Calculates the confidence ellipse for the true mean of the distribution under the assumption of multivariate normality of shot coordinates. The coordinates may be correlated and have unequal variances. The confidence ellipse gives the iso-probability contour, the points on its rim all have the same Mahalanobis distance to the center. The result also includes the ellipse based on a robust estimate for the covariance matrix of the coordinates using the MCD algorithm (from package `robustbase`). The confidence ellipse generalizes to three-dimensional data.

```
## circular error probable
getCEP(DFscar17, type=c("GrubbsPatnaik", "Rayleigh"), level=0.5,
       dstTarget=100, conversion="yd2in")

$CEP
       GrubbsPatnaik Rayleigh
unit          0.8415   0.8290
MOA           0.8036   0.7917
SMOA          0.8415   0.8290
milrad        0.2337   0.2303

$ellShape
aspectRatio  flattening
     1.4503      0.3105

$ctr
    X     Y
2.599 2.299

## confidence ellipse
getConfEll(DFscar17, level=0.95,
           dstTarget=100, conversion="yd2in")

$ctr
    X     Y
2.599 2.299

$ctrRob
    X     Y
```

Wang, Yang, Jia, and Wang (2013); Wang, Yang, Yan, Wang, and Song (2014); Williams (1997).

```
2.804 2.283

$cov
        X       Y
X  0.4492 -0.1695
Y -0.1695  0.6253

$covRob
        X       Y
X 0.03677 0.00779
Y 0.00779 1.97410

$size
       semi-major semi-minor
unit       2.4900     1.7168
MOA        2.3778     1.6395
SMOA       2.4900     1.7168
milrad     0.6917     0.4769

$sizeRob
       semi-major semi-minor
unit        4.099     0.5592
MOA         3.915     0.5340
SMOA        4.099     0.5592
milrad      1.139     0.1553

$shape
aspectRatio  flattening       trace         det
     1.4503      0.3105      1.0745      0.2522

$shapeRob
aspectRatio  flattening       trace         det
    7.33035     0.86358     2.01087     0.07253

$magFac
[1] 2.918
```

Function `getRayParam()` estimates the Rayleigh distribution's radial precision parameter σ together with its radial standard deviation $\text{RSD} = \sigma\sqrt{\frac{4-\pi}{2}}$, and its mean radius $\text{MR} = \sigma\sqrt{\frac{\pi}{2}}$, including parametric confidence intervals.

```
## Rayleigh parameter estimates with 95% confidence interval
getRayParam(DFscar17, level=0.95)

$sigma
  sigma sigCIlo sigCIup
```

```
 0.7041  0.5608  1.0976

$RSD
    RSD RSDciLo RSDciUp
 0.4613  0.3674  0.7191

$MR
    MR MRciLo MRciUp
0.8825 0.7029 1.3756
```

3.2.2 Hit probability for a given region

Given a circle or sphere with radius r around the true mean of the bullet hole distribution, `getHitProb()` estimates the expected fraction of shots that has at most distance r to the group center. The estimated fraction of shots is the same as the estimated probability for one shot to lie in the circle with radius r. The probability can be calculated using the correlated bivariate normal, Grubbs-Pearson χ^2, Grubbs-Patnaik χ^2, Grubbs-Liu χ^2, and Rayleigh distribution as explained in section 3.2.1.

In the example given below, we plug in the results for the 50%-CEP as calculated by `getCEP()` in section 3.2.1 for r, and therefore expect a hit probability of 50%.

```
## for the Grubbs-Patnaik estimate
getHitProb(DFscar17, r=0.8414825, unit="in", accuracy=FALSE,
           dstTarget=100, conversion="yd2in", type="GrubbsPatnaik")

GrubbsPatnaik
          0.5

## for the Rayleigh estimate
getHitProb(DFscar17, r=0.8290354, unit="in", accuracy=FALSE,
           dstTarget=100, conversion="yd2in", type="Rayleigh")

Rayleigh
     0.5
```

Another calculation gives the estimated fraction of shots within a circle with radius 1 MOA.

```
getHitProb(DFscar17, r=1, unit="MOA", accuracy=FALSE,
           dstTarget=100, conversion="yd2in", type="CorrNormal")

CorrNormal
    0.6508
```

3.2.3 Extrapolating CEP and confidence ellipse to different distances

Function `getCEP()` returns the radius of the circular error probable (CEP) in absolute and angular size units, as does `getConfEll()` for the size of the confidence ellipse (section 3.2.1). Since angular size measures can be converted back to absolute size for arbitrary distances (3.5.1), it is possible to estimate the absolute size of the CEP and confidence ellipse for distances different than the one a group was actually shot at.

Given an observed group shot at 100 yd, one might, for example, calculate the radius of the circle at 300 m that is expected to contain 50% of the shots. This calculation is highly idealized as it makes the assumption that all influences on precision scale linearly with distance. Under most circumstances, this assumption is invalid. Generally, extrapolating beyond observed data can often be misleading. However, projecting CEP to slightly different distances might still give a sufficient approximation.

```
## 50% circular error probable for group shot at 100yd
CEP100yd <- getCEP(DFscar17, type=c("GrubbsPatnaik", "Rayleigh"),
                   level=0.5, dstTarget=100, conversion="yd2in")

## CEP in absolute and angular size units
CEP100yd$CEP

       GrubbsPatnaik Rayleigh
unit          0.8415   0.8290
MOA           0.8036   0.7917
SMOA          0.8415   0.8290
milrad        0.2337   0.2303

## extract CEP in MOA
CEPmoa <- CEP100yd$CEP["MOA", c("GrubbsPatnaik", "Rayleigh")]

## 50% CEP in inch for the same group extrapolated to 100m
fromMOA(CEPmoa, dst=100, conversion="m2in")

GrubbsPatnaik      Rayleigh
       0.9203        0.9066
```

Given a group shot at 100 yd, one may be interested in the expected fraction of shots within a circular region with radius $r = 1$ inch around the group center at the distance of 100 m (section 3.2.2). To this end, we first convert 1 inch at 100 m to MOA, and then supply the MOA value to `getHitProb()`.

```
## 1 inch at 100 m in MOA
MOA <- getMOA(1, dst=100, conversion="m2in")

getHitProb(DFscar17, r=MOA, unit="MOA", accuracy=FALSE,
           dstTarget=100, conversion="yd2in", type="GrubbsPatnaik")
```

```
GrubbsPatnaik
       0.5545
```

3.2.4 Literature related to CEP

The literature on the circular error probable (CEP) is extensive and diverse: Applications for CEP are found in areas such as target shooting, missile ballistics, or positional accuracy of navigation and guidance systems like GPS. The statistical foundations in quadratic forms of normal variables are important for analyzing the power of inference tests. The Hoyt and Rayleigh distribution have applications in (wireless) signal processing.

The following list is by no means intended to be complete. Beware that the quality of the cited articles is not uniformly high. The relevant publications may be roughly categorized into different groups:

- Articles that develop a CEP estimator or the modification of one – e. g., RAND-234 (RAND Corporation, 1952), modified RAND-234 (Pesapane & Irvine, 1977), Grubbs (1964a), Rayleigh (Culpepper, 1978; Saxena & Singh, 2005; H. P. Singh, 1992), Ethridge (1983), Spall and Maryak (1992), correlated bivariate normal (DiDonato & Jarnagin, 1961a; Evans et al., 1985). Some articles focus on the confidence intervals for CEP (DiDonato, 2007; Sathe, Joshi, & Nabar, 1991; Taub & Thomas, 1983b; Thomas, Crigler, Gemmill, & Taub, 1973; Zhang & An, 2012).
- Articles or Master's theses comparing the characteristics of CEP estimators in different scenarios (Blischke & Halpin, 1966; Elder, 1986; Kamat, 1962; McMillan & McMillan, 2008; Moranda, 1959, 1960; Nelson, 1988; Puhek, 1992; Tongue, 1993; Taub & Thomas, 1983a; Wang, Jia, Yang, & Wang, 2013; Wang, Yang, et al., 2013; Wang et al., 2014; Williams, 1997).
- Publications studying the correlated bivariate normal distribution re-written in polar coordinates radius and angle (Chew & Boyce, 1962; Greenwalt & Shultz, 1962; Harter, 1960; Hoover, 1984; Hoyt, 1947). The distribution of the radius is known as the Hoyt (1947) distribution. The closed form expression for its cumulative distribution function has only recently been identified as the symmetric difference between two Marcum Q-functions (Paris, 2009a, 2009b). The latter are special cases of the non-central χ^2-distribution (Nuttall, 1975).
- DiDonato and Jarnagin (1961a, 1961b, 1962a, 1962b); Evans et al. (1985) develop methods to use the correlated bivariate normal distribution for CEP estimation when systematic accuracy bias must be taken into account. This requires integrating the distribution over a disc that is not centered on the true mean of the shot group but on the point of aim. This so-called *offset circle probability* is the probability of a quadratic form of a normal variable (Duchesne & Lafaye de Micheaux, 2010). The exact distribution of quadratic forms is a weighted average of non-central χ^2-distributions and difficult to calculate without numerical tools. Therefore, the Patnaik (1949) two-moment central χ^2-approximation or the Pearson (Imhof, 1961; Pearson, 1959) three-moment central χ^2-approximation are often used. Recently, (Liu et al., 2009) proposed a four-moment non-central χ^2-approximation.
- A number of articles present algorithms for the efficient numerical calculation of the Hoyt

cumulative distribution function (cdf), as well as for its inverse, the quantile function (DiDonato, 2004, 2007; Pyati, 1993; Shnidman, 1995). Numerical algorithms to efficiently and precisely calculate the distribution of quadratic forms of normal random variables were proposed by Davies (1980); Farebrother (1984, 1990); Imhof (1961); Sheil and O'Muircheartaigh (1977). A comparison and implementation can be found in Duchesne and Lafaye de Micheaux (2010).
- The Spherical Error Probable is developed in DiDonato (1988); N. Singh (1962, 1970).

3.3 Plotting scaled bullet holes on a target background

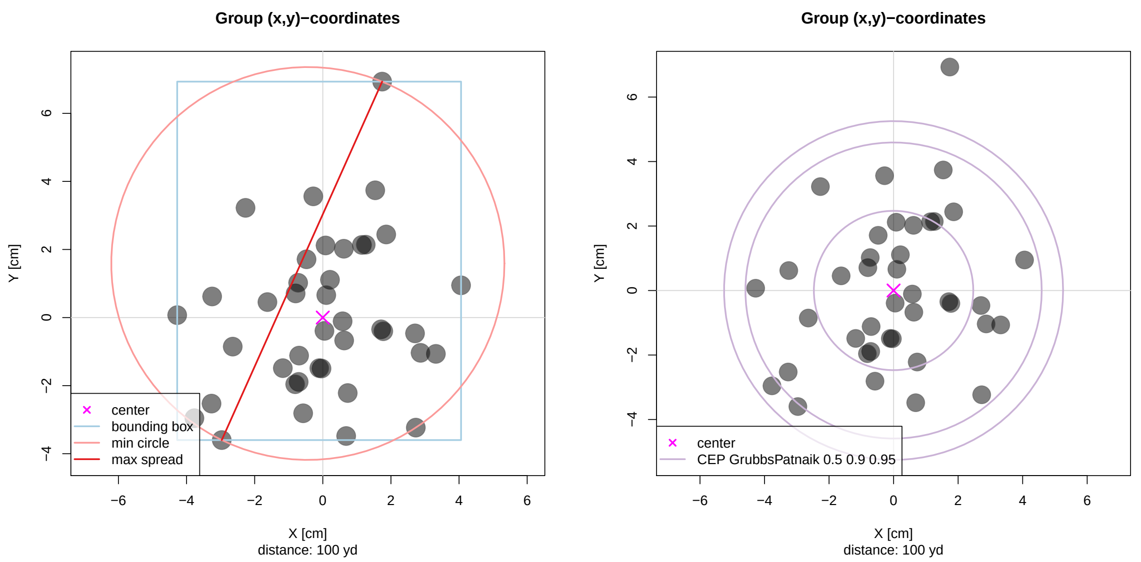
Function `drawGroup()` serves to illustrate a group of bullet holes by drawing the holes to scale on a target background, possibly adding the following features:

- The diagram can be drawn in original measurement units, in absolute size units m, cm, mm, yd, ft, in, or in angular measures MOA, SMOA, milrad.
- A target background can be selected from a number of pre-defined circular target types from different shooting federations (ISSF, DSB, BDS, BDMP, see `help(targets)`). Targets can also be plotted just by themselves using `drawTarget()`.
- Precision indicators can be added to the plot individually:
  - (Minimum-area) bounding box with diagonal
  - Minimum enclosing circle
  - Maximum group spread
  - Circle with mean distance to group center
  - (Robust) confidence ellipse
  - Circular error probable CEP
- If a known target is supplied, the simulated ring value for each shot can be displayed (see section 3.4)

`drawGroup()` invisibly returns all the information that is shown in the diagram converted to the requested measurement unit. In the following example, the original measurement unit for (x, y)-coordinates was inch, the group is here drawn converted to cm. The second example shows how to plot a CEP estimator for multiple levels.

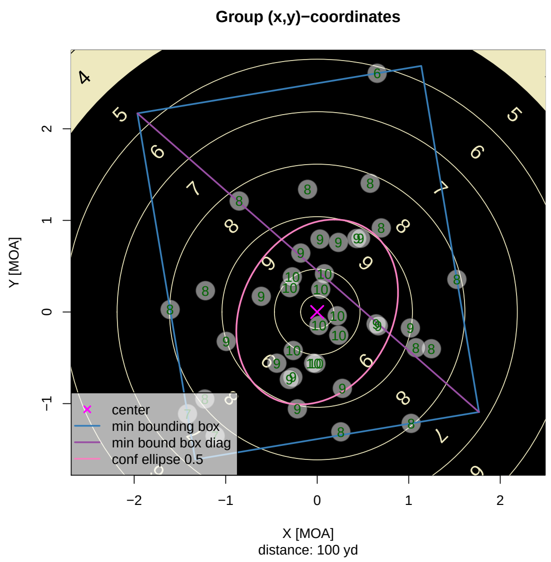
```
library(shotGroups, verbose=FALSE)       # load shotGroups package
dg1 <- drawGroup(DFcciHV, xyTopLeft=TRUE, bb=TRUE, minCirc=TRUE,
                 maxSpread=TRUE, scaled=TRUE, dstTarget=100,
                 conversion="yd2in", caliber=5.56, unit="cm", alpha=0.5,
                 target=NA)

## minimum enclosing circle parameters in cm
dg1$minCirc

$ctr
[1] -0.4395  1.5890
```

```
$rad
[1] 5.771

## show Grubbs CEP estimate for 50%, 90% and 95%
dg2 <- drawGroup(DFcciHV, xyTopLeft=TRUE, CEP="GrubbsPatnaik", scaled=TRUE,
                 level=c(0.5, 0.9, 0.95), dstTarget=100, conversion="yd2in",
                 caliber=5.56, unit="cm", alpha=0.5, target=NA)

## Grubbs CEP estimate for 50%, 90% and 95%
dg2$CEP

[1] 2.471 4.592 5.254
```



Now draw the group with coordinates converted to MOA, add the minimum-area bounding box, 50%-confidence ellipse, use the ISSF 100 yd target, and show the ring value for each shot (see section 3.4).

```
library(shotGroups, verbose=FALSE)      # load shotGroups package
dg3 <- drawGroup(DFcciHV, xyTopLeft=TRUE, bbMin=TRUE, bbDiag=TRUE,
                 confEll=TRUE, ringID=TRUE, level=0.5, scaled=TRUE,
                 dstTarget=100, conversion="yd2in", caliber=5.56, unit="MOA",
                 alpha=0.5, target="ISSF_100yd")

## simulated total ring count with maximum possible
dg3$ringCount

count   max
  351   400
```



3.4 Simulate ring count

Given the (x, y)-coordinates of a group, bullet diameter, and target type with definition of ring diameters, `simRingCount()` calculates a simulated ring count. This is an idealized calculation as it assumes that bullet holes exactly have the bullet diameter, and that rings exactly have the diameter given in the target definition. The count thus ignores the possibility of ragged bullet holes as well as the physical width of the ring markings. The simulated ring count therefore need not be equal to the calculated ring count from the corresponding physical target.

As an example, we simulate the ring count for the `DFscar17` data from shooting a .308 rifle (bullet diameter 7.62 mm) at 100 yd, using the ISSF target made for rifle shooting at 100 m.

```
library(shotGroups, verbose=FALSE)       # load shotGroups package
## simulated ring count and maximum possible with given number of shots
simRingCount(DFscar17, target="ISSF_100m", caliber=7.62, unit="in")

$count
[1] 71

$max
[1] 100

$rings
 [1] 7 6 7 7 7 7 7 7 8 8
Levels: 10 9 8 7 6 5 4 3 2 1 0
```

3.5 Conversion between absolute and angular size units

In addition to absolute length units, group size is often reported in terms of its angular diameter. Angles can be measured equivalently either in degree or in radian. If x is the angular measurement in radian, and φ the angular measurement in degree for the same angle, then $\frac{x}{2\pi} = \frac{\varphi}{360}$ such that conversion between degree and radian is given by $x = \frac{2\pi}{360} \cdot \varphi$ and $\varphi = \frac{360}{2\pi} \cdot x$ (figure 1).

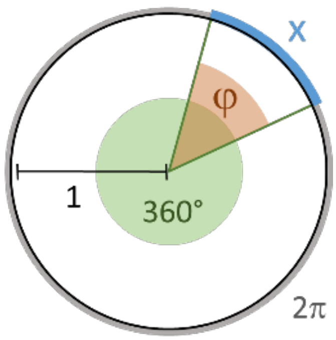


Figure 1: Angle φ (degree) with corresponding arc length x (radian) in the unit circle.

The angular size of an object with absolute size s is its angular diameter at a given distance d. This is the angle α subtended by the object with the line of sight centered on it (figure 2).

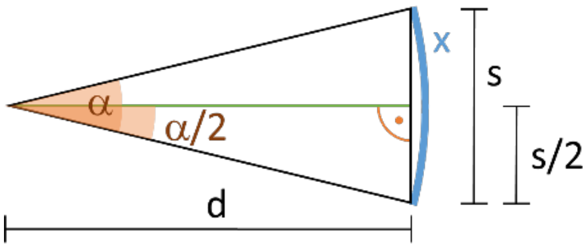


Figure 2: Angular diameter of object with absolute size s at distance to target d. Right triangle formed by d and object of size $s/2$. s corresponds to angle α (degree) and arc length x (radian).

The `shotGroups` package includes functions `getMOA()` and `fromMOA()` to convert from absolute object size to the angular measures MOA, SMOA, milrad and vice versa. The functions need the distance to target d, object sizes s and measurement units for d and s. The option `type` controls which angular measure is returned:

- `type="MOA"`: Convert to/from MOA = minute of angle = arcmin. The circle is divided into 360 degrees, 1 MOA = 1/60 degree such that the circle has $360 \cdot 60 = 21600$ MOA.
- `type="SMOA"`: Convert to/from SMOA = Shooter's MOA = Inches Per Hundred Yards IPHY. 1 inch at 100 yards = 1 SMOA.
- `type="milrad"`: Convert to/from milrad = milliradian = 1/1000 radian. 1 radian is 1 unit of arc length on the unit circle which has a circumference of 2π. The circle is thus divided into $2\pi \cdot 1000 \approx 6283.19$ milrad.

3.5.1 Calculating the angular diameter of an object

Figure 2 shows how the angle α subtended by an object of size s at distance d can be calculated from the right triangle with hypotenuse d and cathetus $s/2$: $\tan\left(\frac{\alpha}{2}\right) = \frac{s}{2} \cdot \frac{1}{d}$, therefore

$\alpha = 2 \cdot \arctan\left(\frac{s}{2d}\right)$.

Assuming that the result from functions $\tan(\cdot)$ and $\arctan(\cdot)$ is in radian, and that distance to target d and object size s are measured in the same unit, this leads to the following formulas for calculating α in MOA, SMOA and x in milrad based on d and s:

- Angle α in MOA: $\alpha = 60 \cdot \frac{360}{2\pi} \cdot 2 \cdot \arctan\left(\frac{s}{2d}\right) = \frac{21600}{\pi} \cdot \arctan\left(\frac{s}{2d}\right)$
- Angle α in SMOA: By definition, size $s = 1$ inch at $d = 100$ yards ($= 3600$ inch) is 1 SMOA.

  Conversion factors to/from MOA are $\frac{21600}{\pi} \cdot \arctan\left(\frac{1}{2 \cdot 3600}\right) \approx 0.95493$ (fairly close to $3/\pi$), and $\frac{\pi}{21600} \cdot \frac{1}{\arctan(1/7200)} \approx 1.04720$ (fairly close to $\pi/3$).

  $\alpha = \frac{\pi}{21600} \cdot \frac{1}{\arctan(1/7200)} \cdot \frac{21600}{\pi} \cdot \arctan\left(\frac{s}{2d}\right) = \frac{1}{\arctan(1/7200)} \cdot \arctan\left(\frac{s}{2d}\right)$
- Arc length x in milrad: $x = 1000 \cdot 2 \cdot \arctan\left(\frac{s}{2d}\right) = 2000 \cdot \arctan\left(\frac{s}{2d}\right)$.

  Conversion factors to/from MOA are $\frac{21600}{2000\pi} \approx 3.43775$ and $\frac{2000\pi}{21600} \approx 0.29089$.

Likewise, object size s can be calculated from an angular measurement and distance to target d:

- From angle α in MOA: $s = 2 \cdot d \cdot \tan\left(\frac{(2\pi/360)(\alpha/60)}{2}\right) = 2 \cdot d \cdot \tan\left(\alpha \cdot \frac{\pi}{21600}\right)$
- From angle α in SMOA: $s = \frac{21600}{\pi} \cdot \arctan\left(\frac{1}{7200}\right) \cdot 2 \cdot d \cdot \tan\left(\alpha \cdot \frac{\pi}{21600}\right)$
- From arc length x in milrad: $s = 2 \cdot d \cdot \tan\left(\frac{x/1000}{2}\right) = 2 \cdot d \cdot \tan(0.0005x)$

```
## convert object sizes in cm to MOA, distance in m
getMOA(c(1, 2, 10), dst=100, conversion="m2cm", type="MOA")

[1] 0.3438 0.6875 3.4377

## convert from SMOA to object sizes in inch, distance in yard
fromMOA(c(0.5, 1, 2), dst=100, conversion="yd2in", type="SMOA")

[1] 0.5 1.0 2.0

## convert from object sizes in mm to milrad, distance in m
fromMOA(c(1, 10, 20), dst=100, conversion="m2mm", type="milrad")

[1]  100 1000 2000
```

3.5.2 Less accurate calculation of angular size

Sometimes, a slightly different angular size is reported as corresponding to absolute size s at distance d: This is the angle α' subtended by the object if it "sits" on the line of sight (figure 3). α' can be calculated from the right triangle with hypotenuse d and cathetus s: $\tan(\alpha') = \frac{s}{d}$, therefore $\alpha' = \arctan(\frac{s}{d})$.

If size s is small compared to distance d, the difference between the actual angular diameter α

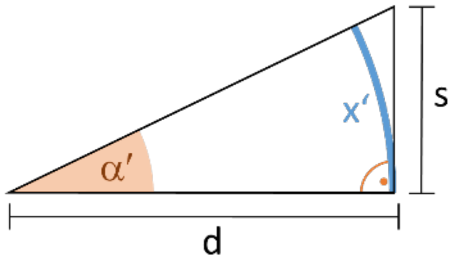


Figure 3: Object "sits" on line of sight: right triangle formed by distance to target d and object of size s. s corresponds to angle α' (degree) and arc length x' (radian).

and approximate angular size α' is negligible, but it becomes noticeable once s gets bigger in relation to d (figure 4).

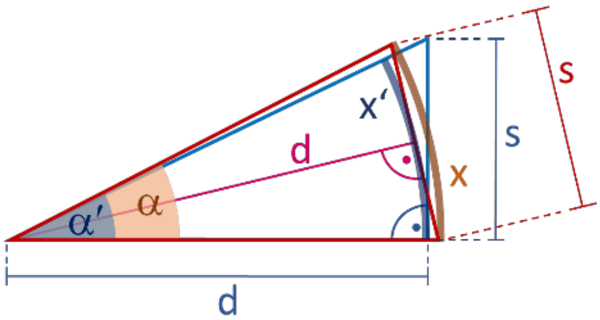


Figure 4: Comparison between actual angular diameter α (red) and the approximate angular size α' (blue) as well as between arc lengths x (red) and x' (blue) corresponding to s at distance d.

3.6 Included data sets

The `shotGroups` package includes a number of empirical data sets with shooting results:

- `DF300BLK`: One group of shooting a Noveske AR-15 rifle in 300BLK at 100 yd with factory ammunition (20 observations)[3]
- `DF300BLKhl`: Three groups of shooting a Noveske AR-15 rifle in 300BLK at 100 yd with handloaded ammunition (60 observations, see footnote 3)
- `DFcciHV`: Two groups of shooting a PWS T3 rifle in .22LR at 100 yd (40 observations, see footnote 3)
- `DFcm`: Several groups of shooting a 9x19mm pistol at 25 m (487 observations)
- `DFtalon`: Several groups of shooting a Talon SS air rifle at 10 m (180 observations)[4]
- `DFsavage`: Several groups of shooting a Savage 12 FT/R rifle in .308 Win at distances from 100 to 300 m (180 observations, see footnote 4)

[3]Thanks: David Bookstaber `http://ballistipedia.com/`
[4]Thanks: Charles & Paul McMillan `http://statshooting.com/`

- DFscar17: One group of shooting an FN SCAR 17 rifle in .308 Win at 100 yd (10 observations, see footnote 3)

4 TODO

- CEP parametric/bootstrap CIs
- Human-readable output from functions compareGroups(), groupLocation(), groupShape(), groupSpread() by using print() methods
- Function which accepts extreme order statistics (maximum spread) to allow inference for Rayleigh parameters σ, RSD, MR (Taylor & Grubbs, 1975; Taylor, 1977)
- Add formulas for calculated statistics to this vignette
- Consider platykurtic distribution type that allows for more near misses than normal distribution; spatial Poisson process
- Allow dates be associated with group data to track accuracy and precision performance over time
- Allow 3D data where applicable

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