

Package ‘woylier’

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Title Alternative Tour Frame Interpolation Method

Version 0.0.5

Description This method generates a tour path by interpolating between d-D frames in p-D using Givens rotations. The algorithm arises from the problem of zeroing elements of a matrix. This interpolation method is useful for showing specific d-D frames in the tour, as opposed to d-D planes, as done by the geodesic interpolation. It is useful for projection pursuit indexes which are not s invariant. See Buja et al (2005) <[doi:10.1016/S0169-7161\(04\)24014-7](https://doi.org/10.1016/S0169-7161(04)24014-7)>.

Depends R (>= 4.1)

Imports tourr, geozoo, dplyr, tibble

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Encoding UTF-8

RoxygenNote 7.2.1

Suggests knitr, rmarkdown, purrr, ggplot2, ash, testthat (>= 3.0.0)

Config/testthat/edition 3

VignetteBuilder knitr

NeedsCompilation no

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add_path	<i>Overlay paths of interpolation on the sphere</i>
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Description

Overlay paths of interpolation on the sphere

Usage

```
add_path(proj_space, path)
```

Arguments

proj_space	n number of points on the surface of sphere
path	interpolated path

Value

data frame with interpolated path and points on sphere surface

Examples

```
p <- 4
base1 <- tourr::basis_random(p, d=1)
base2 <- tourr::basis_random(p, d=1)
path <- givens_full_path(base1, base2, nsteps=10)
sp <- generate_space_view(p=p)
sp_path <- add_path(sp, path)

tourr::animate_xy(sp_path[,1:4], col=sp_path$type)
```

generate_space_view	<i>Generate the background sphere or torus</i>
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Description

Generate the background sphere or torus

Usage

```
generate_space_view(n = 1000, p = 3, d = 1)
```

Arguments

n number of points on the sphere
p dimension of data
d dimension of projection

Value

n number of points on the surface of sphere

Examples

```
p <- 4  
sp <- generate_space_view(p=p)
```

givens_full_path *Construct full interpolated frames*

Description

Construct full interpolated frames

Usage

```
givens_full_path(Fa, Fz, nsteps)
```

Arguments

Fa starting pxd frame
Fz target pxd frame
nsteps number of steps of interpolation

Value

array with nsteps matrix. Each matrix is interpolated frame in between starting and target frames.

Examples

```
p <- 4  
base1 <- tourr::orthonormalise(tourr::basis_random(p, d=1))  
base2 <- tourr::orthonormalise(tourr::basis_random(p, d=1))  
path <- givens_full_path(base1, base2, nsteps=10)
```

grand_tour_givens *Create a grand tour with Givens interpolation*

Description

Create a grand tour with Givens interpolation

Usage

```
grand_tour_givens(d = 2, ...)
```

Arguments

d dimension of projection
... additional parameters to pass through

Value

creates grand tour

Examples

```
data(sine_curve)  
tourr::animate(sine_curve, grand_tour_givens(), tourr::display_xy())
```

guided_tour_givens *Create a guided tour with Givens interpolation*

Description

Create a guided tour with Givens interpolation

Usage

```
guided_tour_givens(  
  index_f,  
  d = 2,  
  alpha = 0.5,  
  cooling = 0.99,  
  max.tries = 25,  
  max.i = Inf,  
  optim = "search_geodesic",  
  n_sample = 100,  
  ...  
)
```

Arguments

<code>index_f</code>	the index function to optimize.
<code>d</code>	target dimensionality
<code>alpha</code>	the initial size of the search window, in radians
<code>cooling</code>	the amount the size of the search window should be adjusted by after each step
<code>max.tries</code>	the maximum number of unsuccessful attempts to find a better projection before giving up
<code>max.i</code>	the maximum index value, stop search if a larger value is found
<code>optim</code>	character indicating the search strategy to use: <code>search_geodesic</code> , <code>search_better</code> , <code>search_better_random</code> , <code>search_polish</code> . Default is <code>search_geodesic</code> .
<code>n_sample</code>	number of samples to generate if <code>search_f</code> is <code>search_polish</code>
<code>...</code>	arguments sent to the <code>search_f</code>

Value

creates guided tour

Examples

```
data(sine_curve)
tourr::animate_xy(sine_curve, guided_tour_givens(tourr::splines2d()), sphere=FALSE)
```

`planned_tour_givens` *A planned tour path using frame-to-frame interpolation.*

Description

The planned tour takes you from one basis to the next in a set order. Once you have visited all the planned bases, you either stop or start from the beginning once more (if `cycle = TRUE`).

Usage

```
planned_tour_givens(basis_set, cycle = FALSE)
```

Arguments

<code>basis_set</code>	the set of bases as a list of projection matrices or a 3d array
<code>cycle</code>	cycle through continuously (<code>TRUE</code>) or stop after first pass (<code>FALSE</code>)

Details

Usually, you will not call this function directly, but will pass it to a method that works with tour paths like [animate](#), [save_history](#) or [render](#).

Value

creates planned tour path

See Also

The [little_tour](#), a special type of planned tour which cycles between all axis parallel projections.

Examples

```
library(tourr)
twod <- save_history(flea[, 1:3], max = 5)
str(twod)
animate_xy(flea[, 1:3], planned_tour_givens(twod))
animate_xy(flea[, 1:3], planned_tour_givens(twod, TRUE))

oned <- save_history(flea[, 1:6], grand_tour(1), max = 3)
animate_dist(flea[, 1:6], planned_tour_givens(oned))
```

sine_curve measurements

Simulated 6D data with a sine curve

Description

The data has 6 columns, labelled V1-V6, where the sine curve is in V5, V6. The other columns are normal samples.

Format

A 500x6 data frame

Examples

```
library(woylier)
data(sine_curve)
plot(sine_curve$V5, sine_curve$V6)
```

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